

## JAXA Status Report Part 2

# SpaceWire devices developed in JAXA's SpaceWire R&D activities in the last 3 years (and coming several years).

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20th SpaceWire Working Group meeting  
at ESTEC



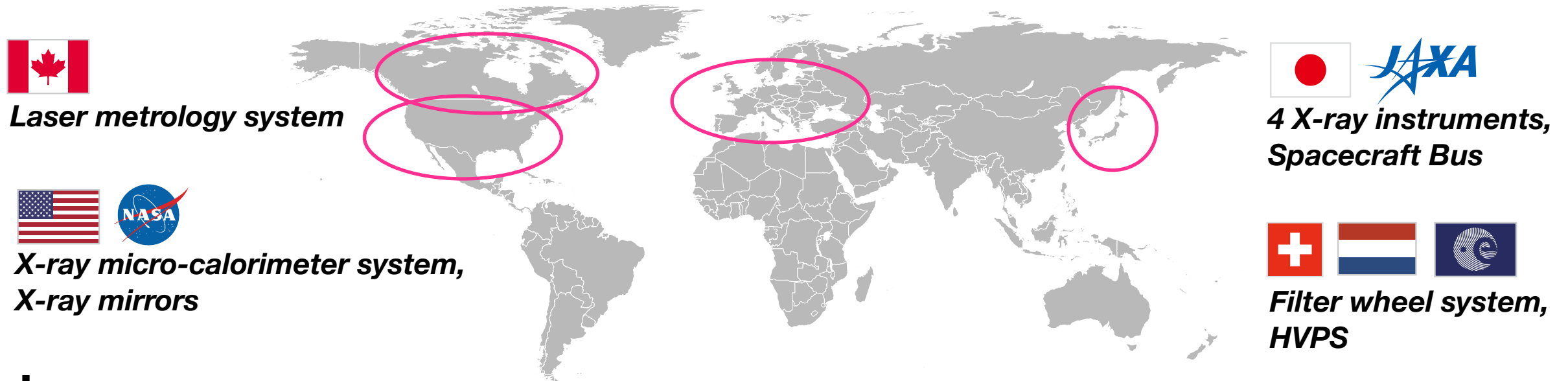
Japan Aerospace Exploration Agency  
Institute of Space and Astronautical Science

# Background - How to develop SpaceWire components for ASTRO-H

## Developments of mission instruments

- SpaceWire was defined as the only data interface between subsystems and the SC bus.
- Multiple institutes(NASA, ESA, SRON, CSA), industries (NEC, MHI, SHI), and universities (>24).

### ASTRO-H Onboard Component map



## What was necessary:

- 1. Standardized SpaceWire device that can be used to develop and test one's onboard component.
  - SpaceWire-to-GigabitEther (JAXA/Shimafuji)
  - SpaceCube Mk2 (NEC/Shimafuji Electric)
- 2. Test environment for large-scale SpaceWire network.
  - SpaceWire microTCA Backplane and modules (MHI/UoO/JAXA)
- 3. Verification scheme
  - SpaceWire I/F layer, RMAP layer, and Telemetry/Command service layer.
  - Portable end-to-end test system that can be connected to the real SC operation software.

Development of SpaceWire devices mainly for ground testing  
in the reliable SpaceWire network project Nov 2010 - Mar 2013.

# 1. Generic SpaceWire I/F : SpaceWire-to-GigabitEther

## Overview

- SpaceWire packet/timecode transfer via TCP/IP.
- No driver software is necessary.
- 4 external SpaceWire ports.

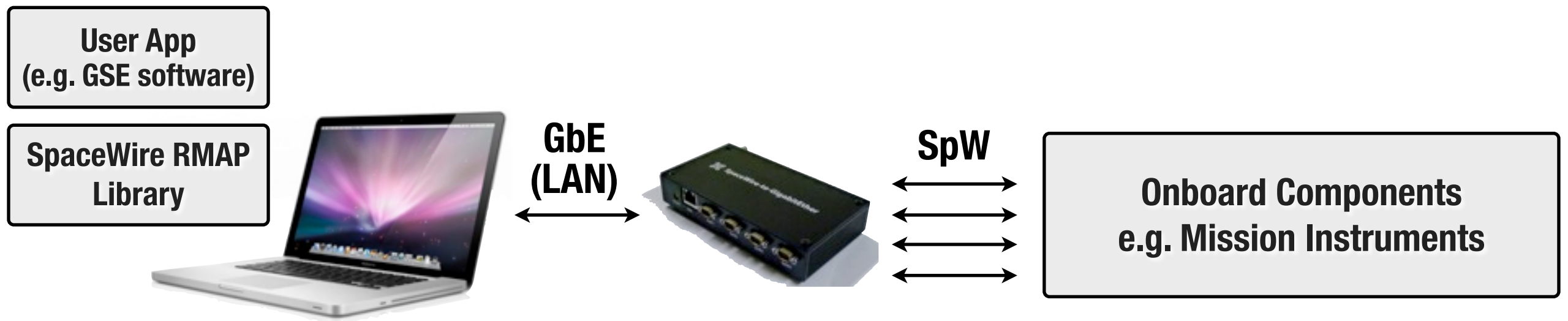
## Performance

- Max 200 MHz SpaceWire link frequency.
- TCP/IP at max 650 Mbps.

## Applications

- GSE software running on ordinary PC.
- Embedded OS programming is not required.
- High throughput data read out of mission instruments.

Available from Shimafuji.



# 1. SpaceWire-to-GigabitEther details

Item	Description	Remarks
Interfaces	SpaceWire x 4 GigabitEthernet x 1	Max 200 MHz SpaceWire link frequencies.
Router	1 Internal SpaceWire Router with 9 ports	
TCP Sockets	2 server sockets on TCP 10030 and 10031	
IP Address	192.168.1.100 (default) Modifiable via web browser	
Supported Systems	Linux/Mac/PC	Others with GbE could be used.
Packet Transfer	Packets with EOP/EEP/no-EOP can be transferred	
TimeCode	Supports both emission and reception on PC	
Software	SpaceWire RMAP GUI or User-dependent Applications	SpaceWire RMAP Library is provided for C++ development.
Size and weight		



# 1. SpaceWire-to-GigabitEther example usages

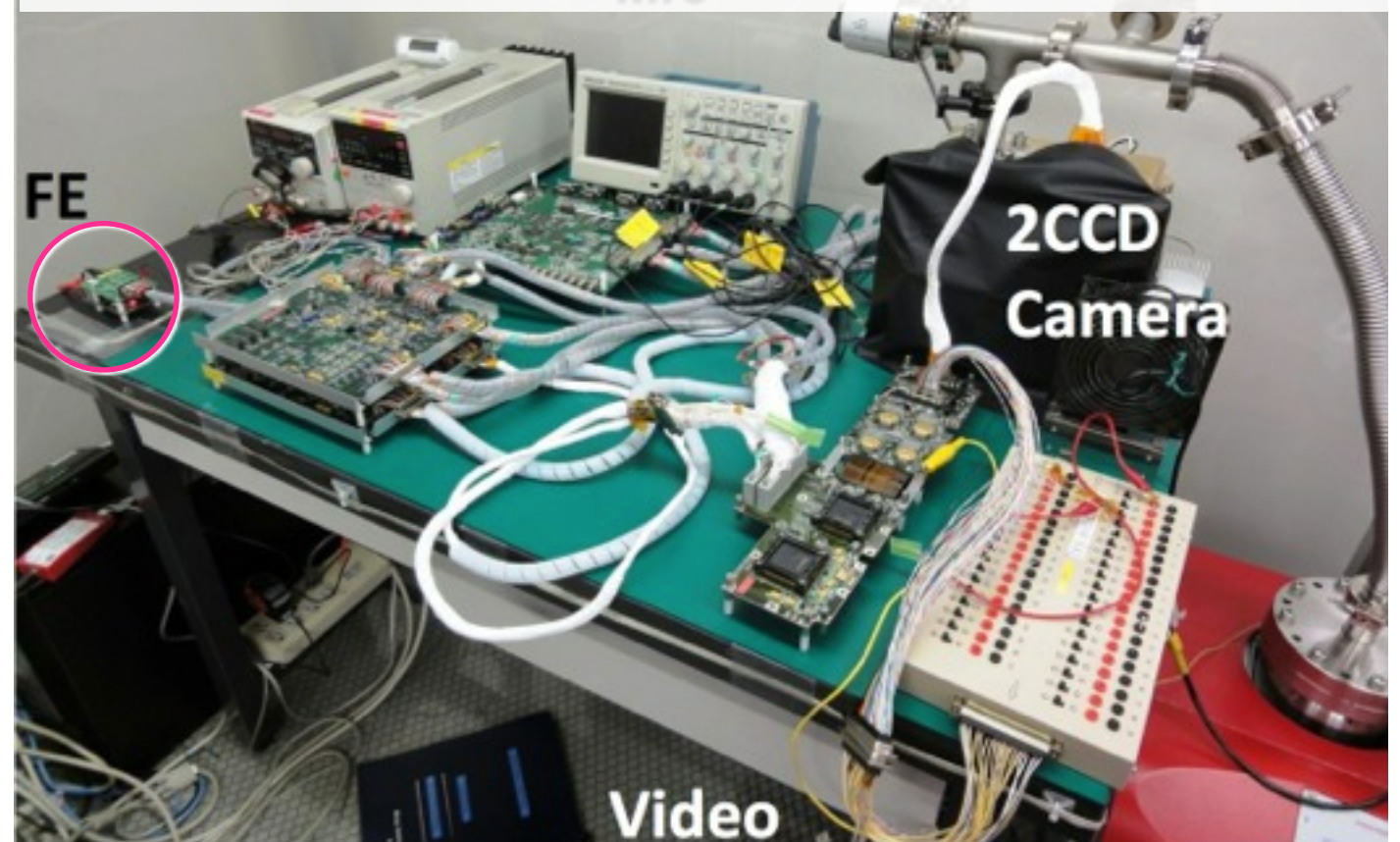
## Mission instrument development

- Used in more than 20 universities/institutes.
- GSE software development in C++ by scientists and engineers in universities and companies.
- RMAP API available in the open-source SpaceWire RMAP Library.
- High speed readout for instrument calibration/test purposes.  
(Max 650Mbps from 4 external SpaceWire links)

Hard X-ray Imager



X-ray CCD Imager



## 2.1 Test environment for large-scale SpaceWire network

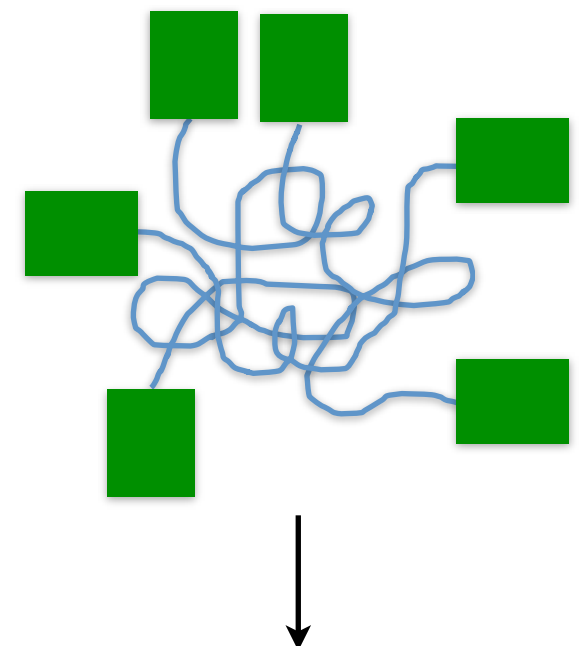
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### Simplification of development and test

- Test of onboard SpaceWire network of a large satellite can involve more than 20-30 subsystems.
- Construction of test environment (placement, cabling, etc) can be problematic.
- Test bed that allows rapid integration can reduce man-hour needed for tests.

### Requirements

- Crate (or subrack) that collects multiple SpaceWire modules, i.e. processor and FPGA boards.
- Rugged mechanical support.
- Good power supply and grounding.
- Good cooling.
- Commercial availability (reduced test cost).
- 100  $\Omega$  transmission line for SpaceWire.



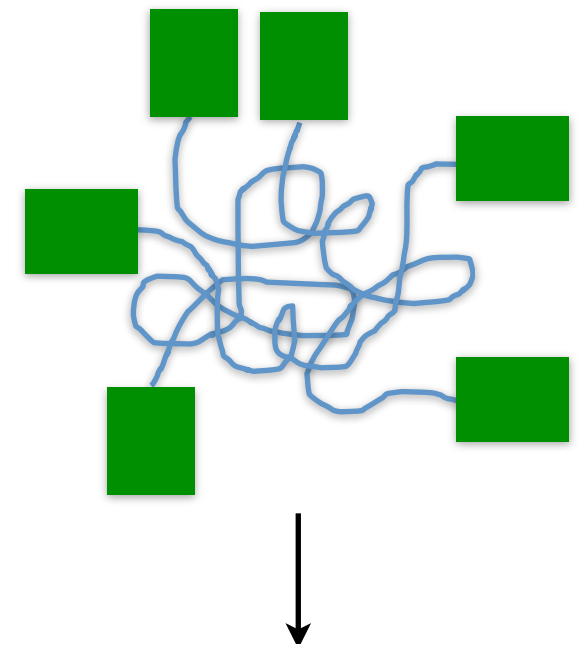
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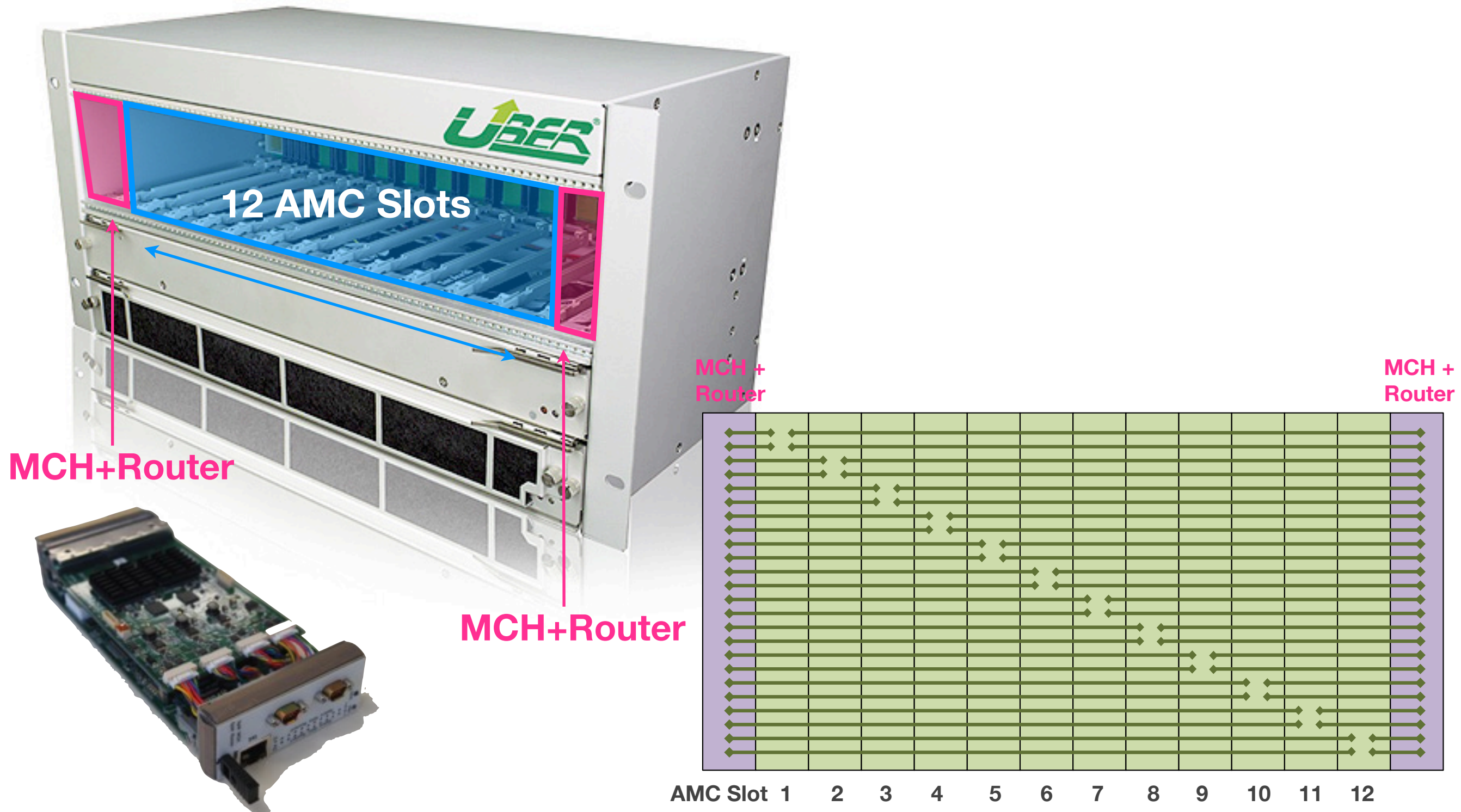


We selected  **$\mu$ TCA<sup>TM</sup>** + **AdvancedMC<sup>TM</sup>**.



## 2.2 Example of commercial 12-slot microTCA backplane

- Collects 12 AMC modules in a normal microTCA crate.
- Router in a crate-controller module (or MicroTCA Carrier Hub; MCH) interconnects 24 links on the backplane.

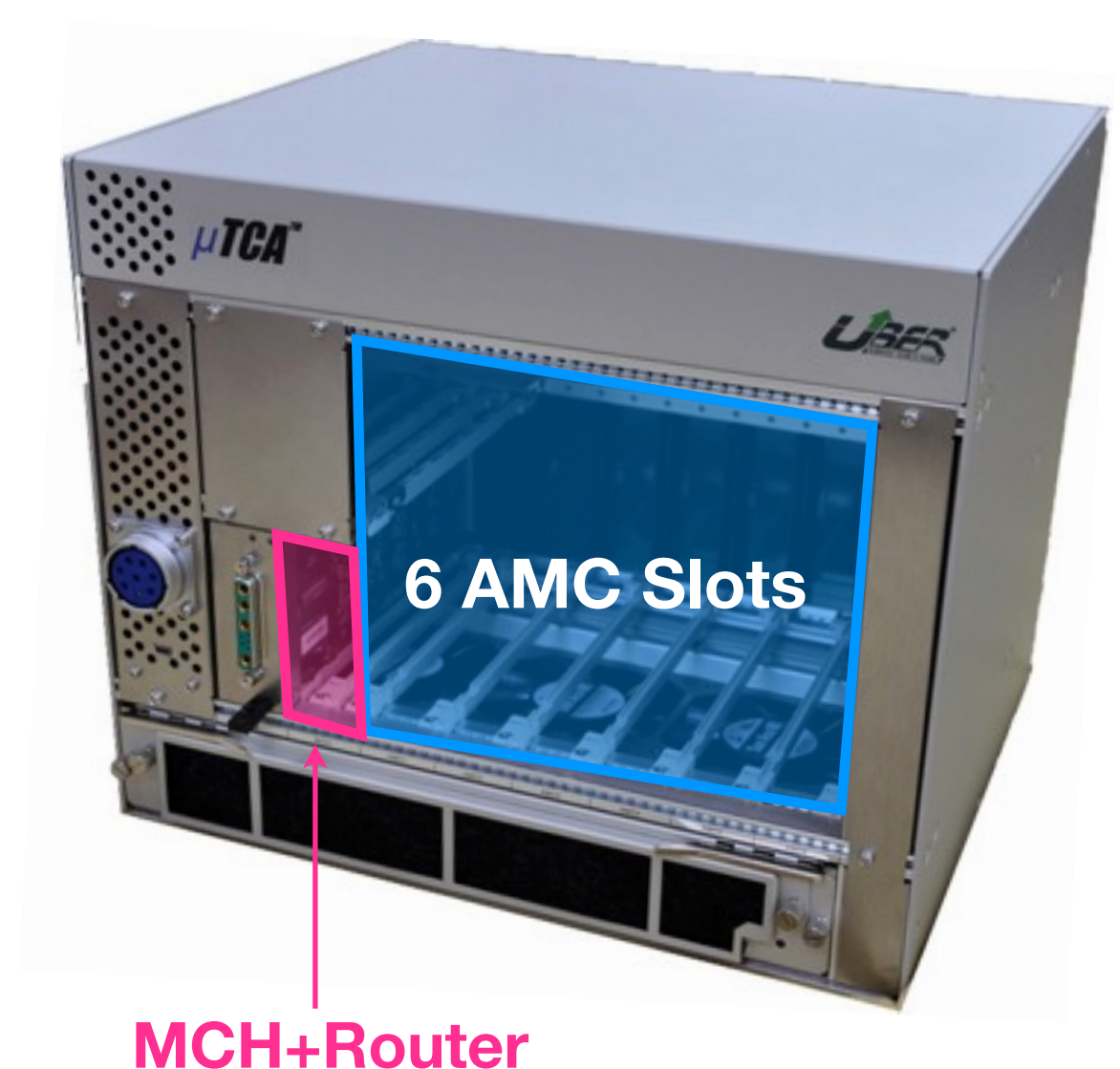
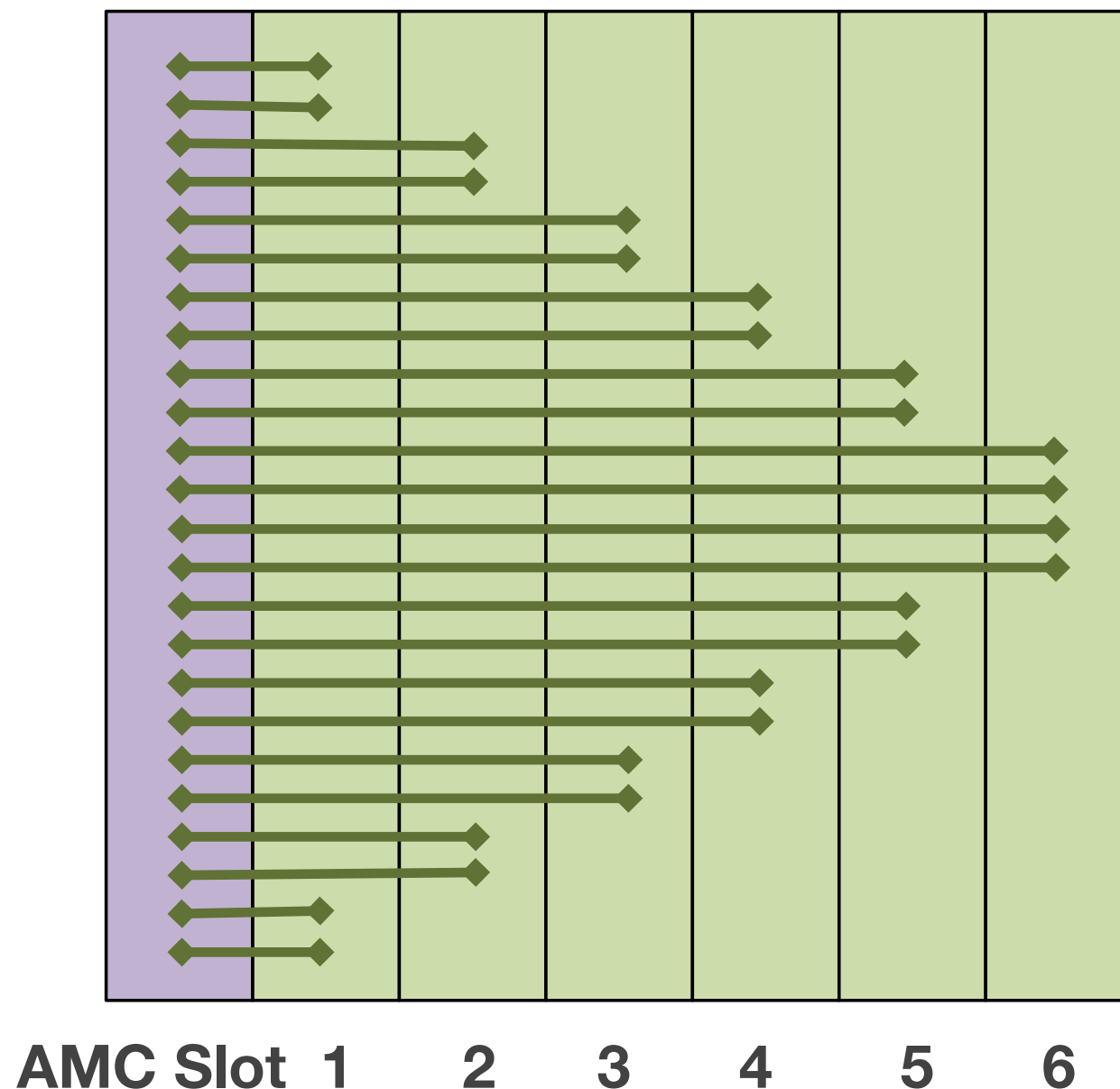




## 2.4 For smaller systems - Customized 6-AMC-slot crate

- We have developed a modified uTCA-like backplane for smaller systems.
- SpaceWire links to redundant-MCH are flipped to non-redundant-MCH.  
i.e. 1 MCH+Router handles at most 24 SpaceWire links from 6 AMC modules.
- Affordable for small experiments, university groups.
- The same AMC modules can be used with modified routing configuration in the router.

### MCH +Router



## 2.5 Available SpaceWire AMC modules

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- For SpaceWire network integration test of JAXA's ASTRO-H satellite, Mitsubishi Heavy Industry, Japan, developed CPU board and General-purpose FPGA board based on the SpaceWire AMC concept.



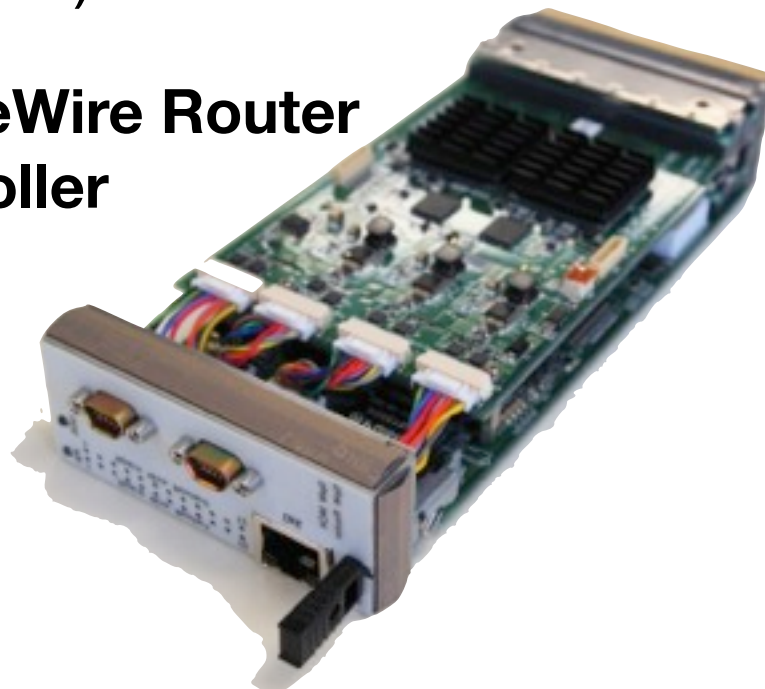
**AMC SpaceWire CPU Board**



**AMC SpaceWire FPGA Board**

- Generic SpaceWire I/F Board, SpaceWire-to-GigabitEther, and 28-port Router modules are available from Shimafuji Electric (support from Japan Space Systems/MEXT).

**28-port SpaceWire Router  
+ Shelf Controller**



**Generic SpaceWire FPGA Module**

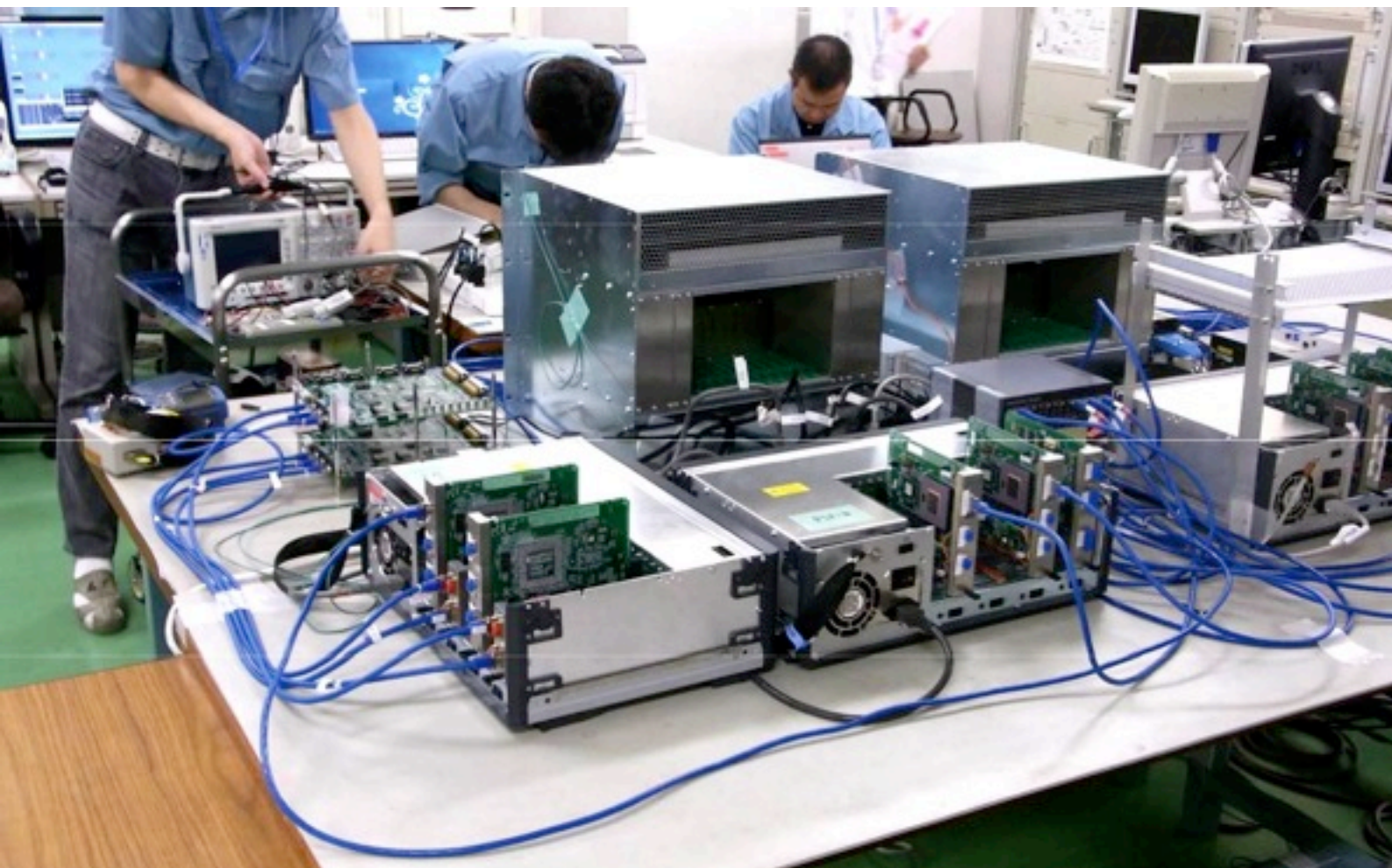




## 2.6 Example usage in ASTRO-H

### SpaceWire Network Test (2011)

- 5 micro-TCA shelves with 10 processor modules and 10 FPGA modules, simulating mission instrument electronics.
- Thanks to the backplane, we could reduce cables, and therefore complexities in constructing a test setup.
- 1 shelf => 1 mission instrument.
- Interface between SC (SMU + DR) and mission instrument electronics was confirmed.
- Optimum value for router timeout duration was recognized (~2ms for A-H).





## 2.7 SpaceWire Traffic Generator - an application of SpW backplane

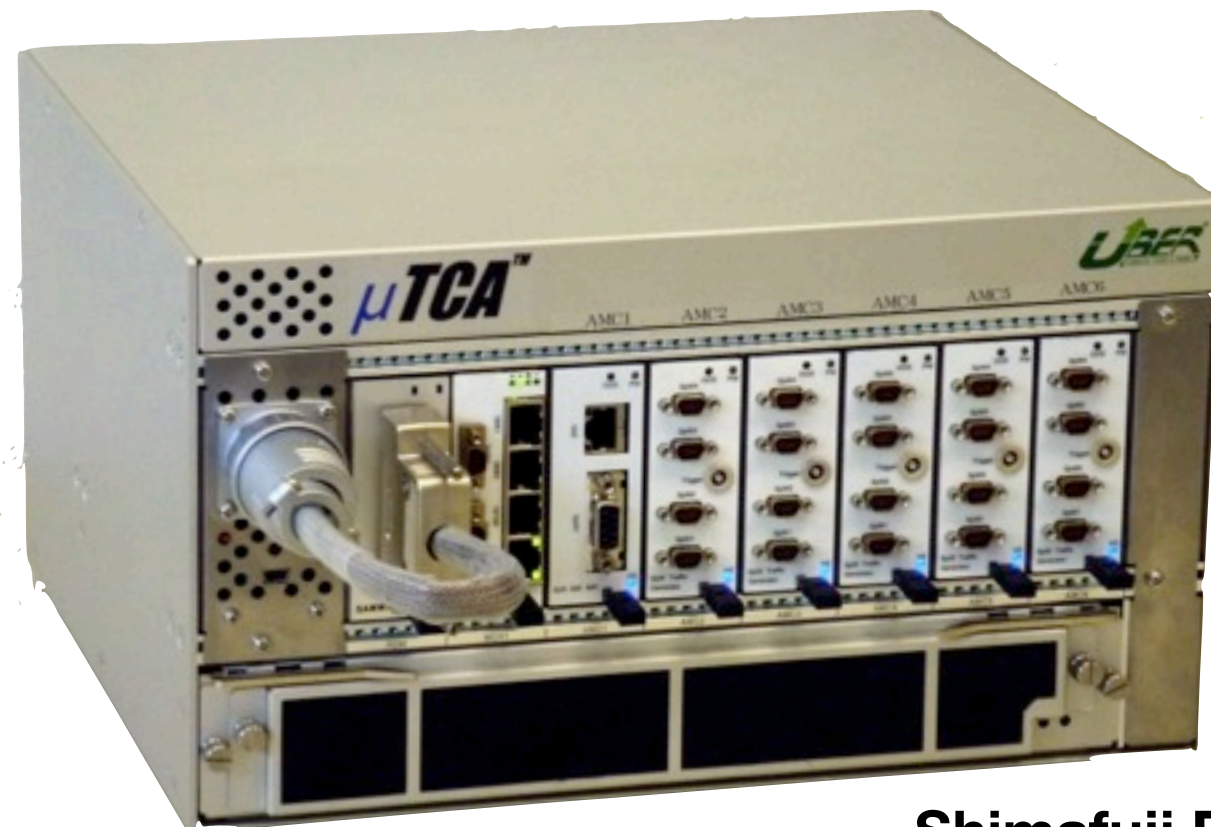
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### Overview

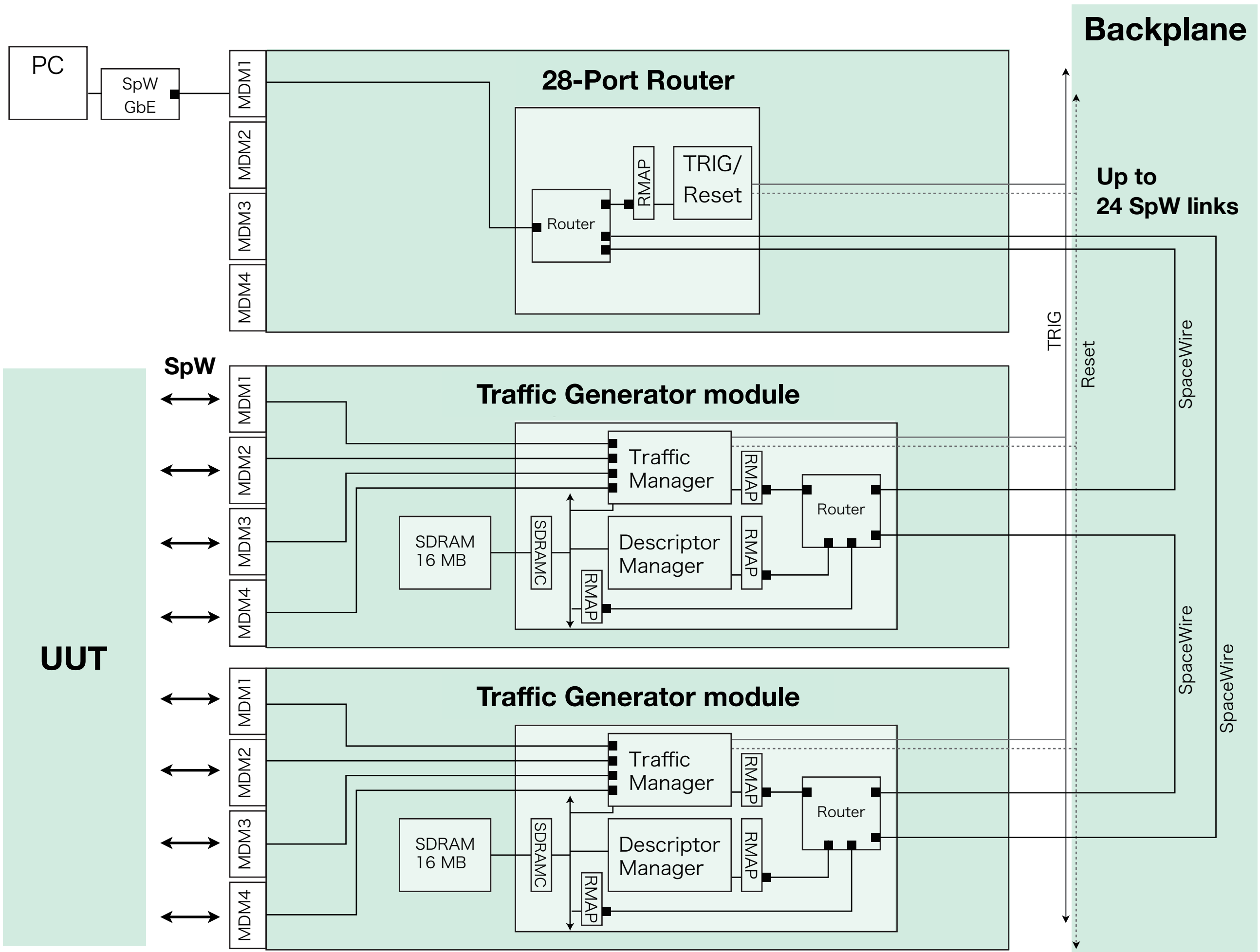
- A SpaceWire uTCA Backplane-based SpaceWire packet generator.
- Sends packets according to a given scenario.
- Records received packets.
- Traffic injection to a large network.
- See Yuasa et al. in SpaceWire Conference 2013.

### Scalable SpaceWire port number

- A SpaceWire Traffic Generator module has 4 output SpaceWire ports.
- 6-slot shelf => Maximum number of output SpaceWire ports of 24.
- 12-slot shelf => 48



Shimafuji Electric/JAXA



# Traffic Generator Control software (Shimafuji)

Traffic Generator Control Software

General | Link | Intervals | Misc1 | Misc2 | Tx/Rx Settings | **Tx** | Tx Log | Rx1 | Rx2 | Test

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Load Tx Data to Memory

Write Address:

From Binary File:

1048576 bytes

Manual Input

00	01	02	03	04	05	06	07	08	09	0A	0B	0D	0E	0F
10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E
1F														

Data Read Back

Address:

Length:  bytes

00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F
10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F
20	21	22	23	24	25	26	27	28	29	2A	2B	2C	2D	2E	2F
30	31	32	33	34	35	36	37	38	39	3A	3B	3C	3D	3E	3F
40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F
50	51	52	53	54	55	56	57	58	59	5A	5B	5C	5D	5E	5F
60	61	62	63	64	65	66	67	68	69	6A	6B	6C	6D	6E	6F
70	71	72	73	74	75	76	77	78	79	7A	7B	7C	7D	7E	7F
80	81	82	83	84	85	86	87	88	89	8A	8B	8C	8D	8E	8F

Load Tx Descriptors

Tx Desc. Entries:

From Binary File:

276 entries

Manual Input

Mode Flag:

Tx Data Address:  Length:

or Timecode:  (HEX) (DEC)

Wait Time:  (DEC, 0 to 16383)

Unit ☐ ns ☒ us ☐ ms ☐ s

Repeat:  (DEC)

Entry:

Trigger

☒ Port 1 ☐ Port 2 ☐ Port 3 ☐ Port 4

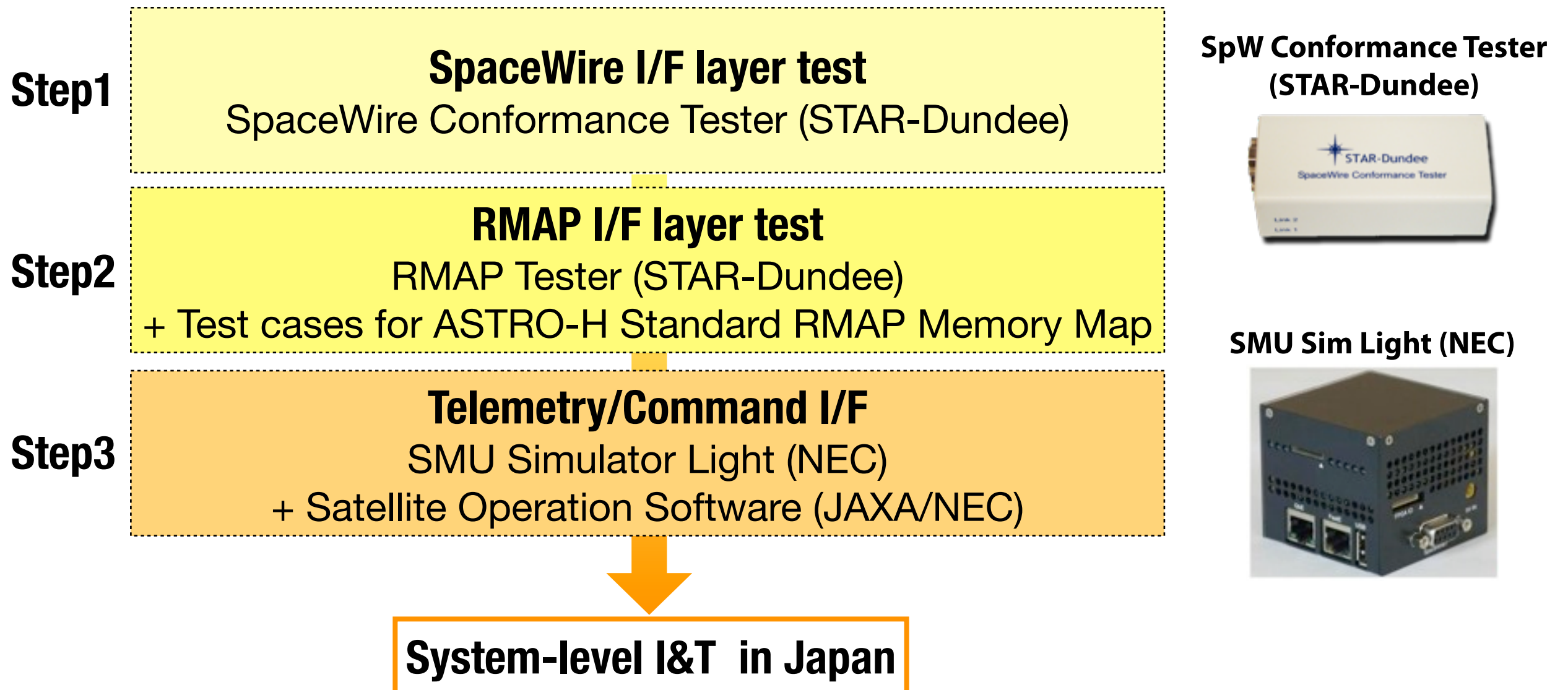


## 3.1 Verification scheme

### Purposes

- To reduce risks of system-level electrical interface test by front-loading end-to-end Telemetry/Command tests at subsystem level.
- Standard verification scheme was defined for ASTRO-H.
- This was possible because SpaceWire is the only data interface (no RS422, no MIL-1553B, nor dedicated interface between SC and subsystems).

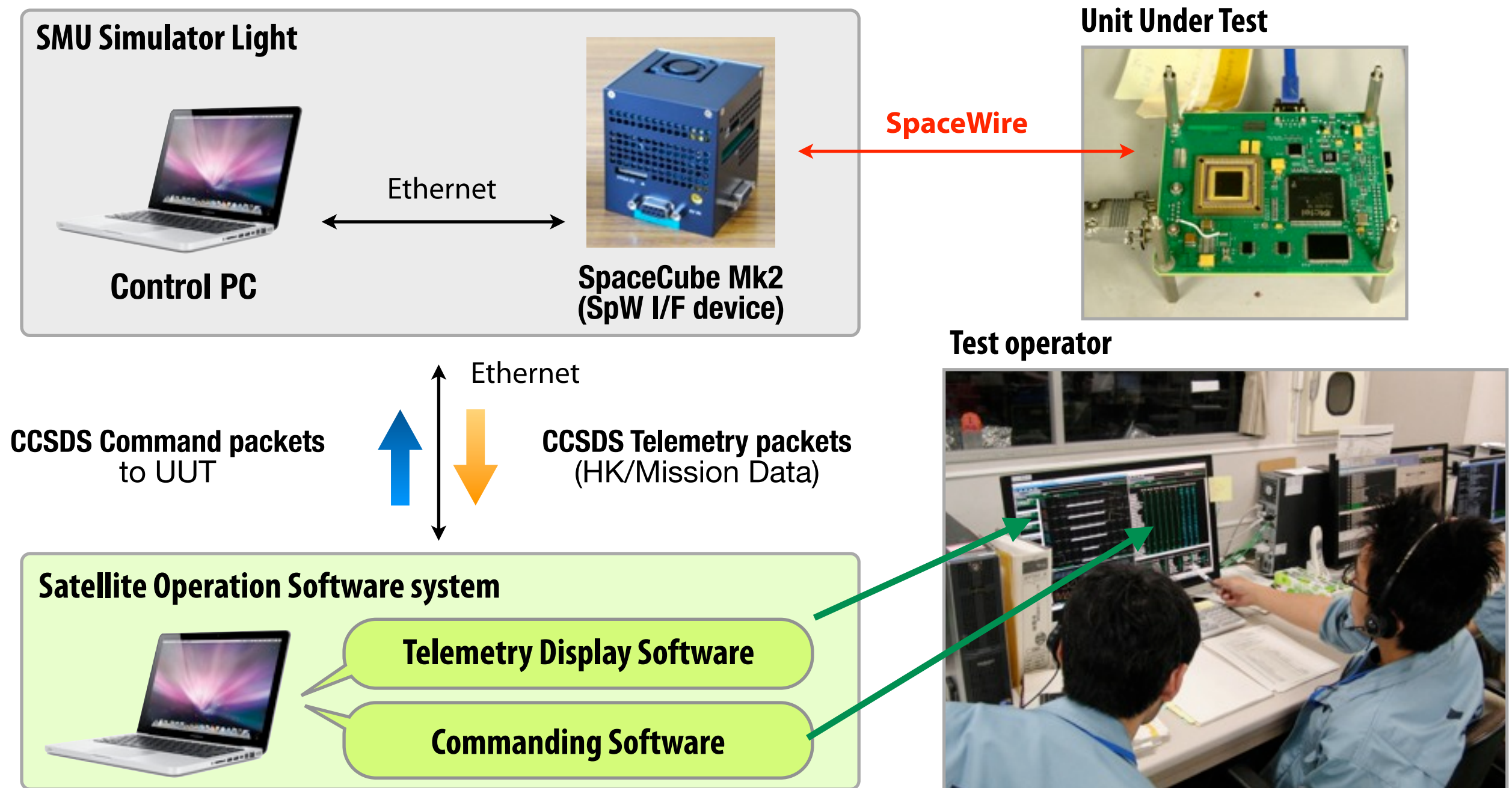
### 3 steps of subsystem-level verification



## 3.2 Satellite Management Unit (SMU) Simulator (NEC/JAXA)

### Overview

- Implements SMU's Telemetry/Command services on the SpaceCube Mk2 computer.
- Interfaces the real satellite operation software (GSTOS).
- Test scenarios/scripts are directly transferred to FM tests and post-launch operations.
- The simulator was distributed to each company/university.
- Helped to find interface problems of subsystems well before the system I&T.





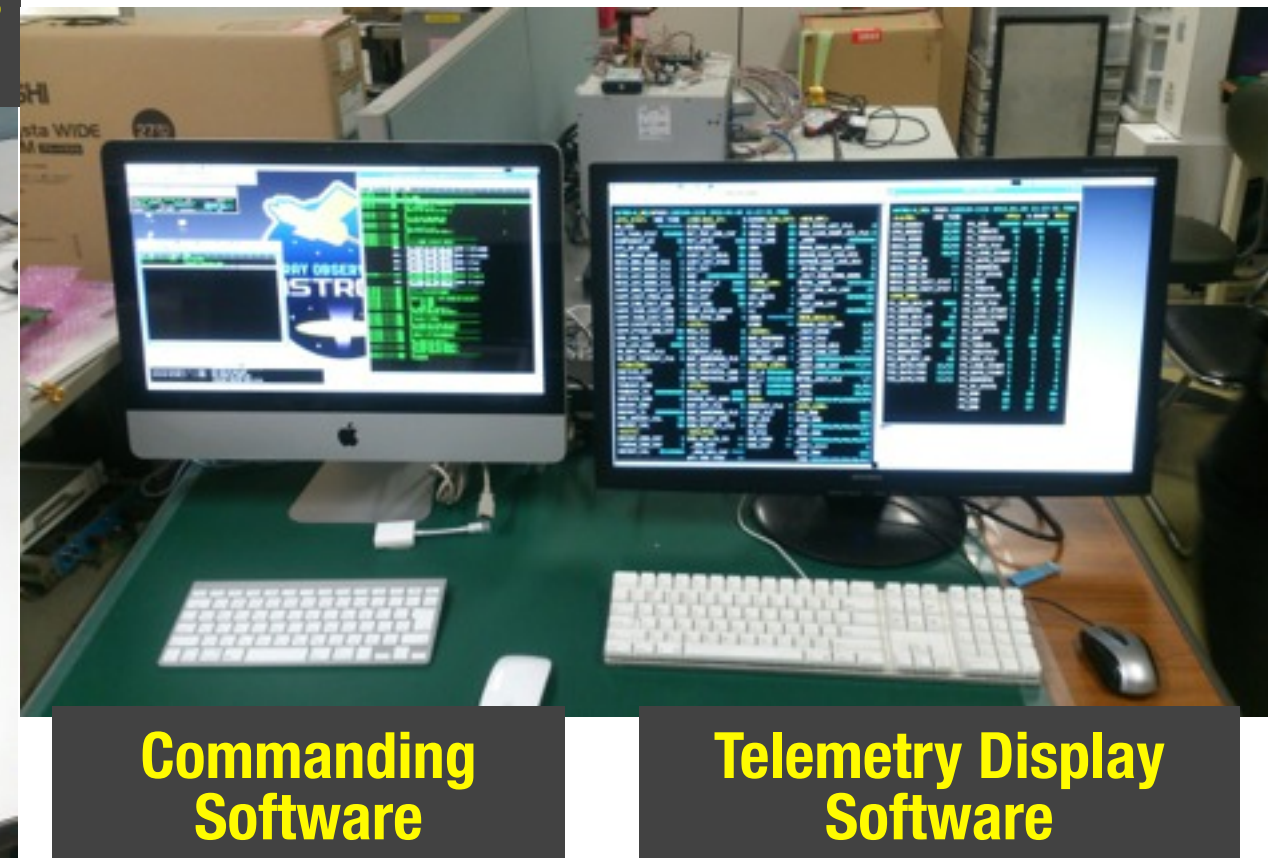
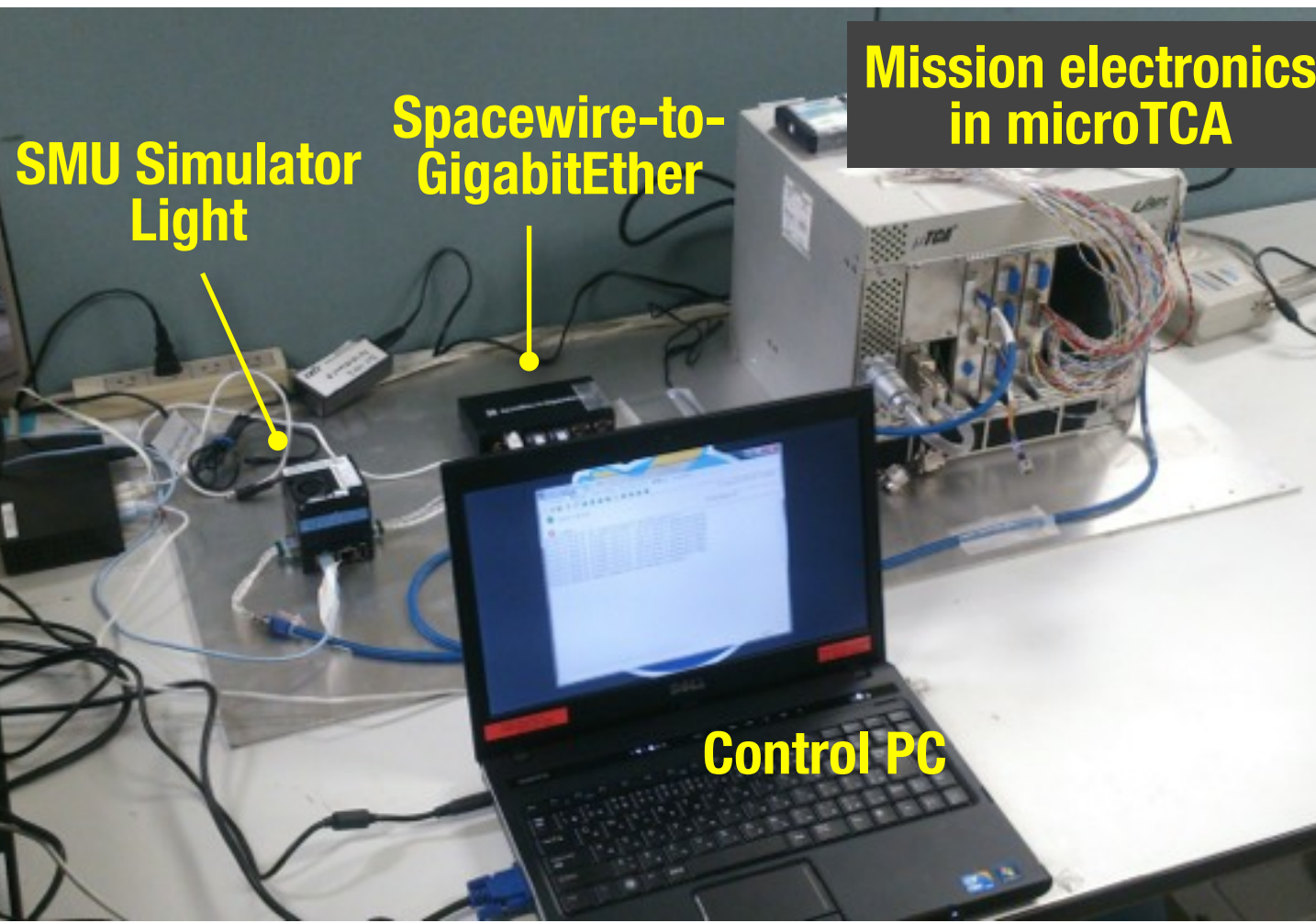
## 3.3 Services implemented in the SMU Simulator

### Communication services

- Command write. --- Single RMAP Write
- HK collection. --- Single RMAP Read
- Request polling and response. --- Polling, then single RMAP Read
- Mission data collection. --- Polling, then multiple RMAP Read

### Test procedure






- Basic communication test of each services.
- Check all defined commands work as expected.
- Check behavior against failure cases.
- Scripted test of command sequence that will be used in the flight operation.
- Telemetry monitoring while commands are sent.





### 3.3 STEP3 tests in various places (with various SpaceWire/RMAP IP cores)

#### Test records

Component	Place	IP Core type		
X-ray instruments	Japan (MHI/Univ.)	 MHI	2011-	
Cooler driver	Japan (SHI)	 NEC	2011-	
ADR cooler driver	NASA/GSFC	 NASA	Nov. 2011, Jun. 2012	
Filter wheel system	Swiss	 ESA	Sep. 2011, Mar. 2012	
Laser metrology system	Canada	 ESA	Jul. 2011, May-Jun. 2013	






- Not only in ASTRO-H, the same SMU Simulator has been used in other JAXA missions such as SPRINT-A space observatory (2013) and HAYABUSA-2 sample return mission (2014).

#### Lessons learned

- Define assumed failure cases clearly/precisely in the design rule document to get coherent response to failures (e.g. response to non-RMAP Protocol ID; incorrect RMAP IP core usage could block further packet reception).
- Portable test environment made oversea tests easy. In the on-site tests, verification of maker's own GSE were also possible based on devices from other suppliers.
- Single data interface design in both of SC bus and mission seems very effective to reduce cost of tests and interface adjustment. (TC over SpaceWire is promising)

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## **4. On-going and near future activities**

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### **New R&D activities from Q2 2013**

- SpaceFibre codec IP developments.
- Non-blocking SpaceWire Router based on framing/segmentation.

### **Activities done by Japan SpaceWire Users Group members**

- SpaceFibre developments (NEC/NTSpace, MELCO)
- SpaceWire Middleware porting to Leon CPU. (Nagoya U./Shimafuji Electric/MHI)
- 24-port Packet Recorder (Shimafuji Electric)
- Lightweight SpaceWire cable (ITTCanon/Junkosha)



# Summary

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- Driven by ASTRO-H, JAXA, together with NEC, Shimafuji Electric, and other companies, has been developing SpaceWire devices for ground testing of satellite components.
- Resulting products are heavily used in on-going projects.
- Some of the products will be internationally available.
- New R&D on SpaceFibre and non-blocking SpaceWire router will start shortly.
- Other players in Japan also actively studying/developing SpaceWire-related components/software.

**Thank you very much for your attention.**

**Welcome comments/requests/advices on JAXA SpaceWire R&D activities.**



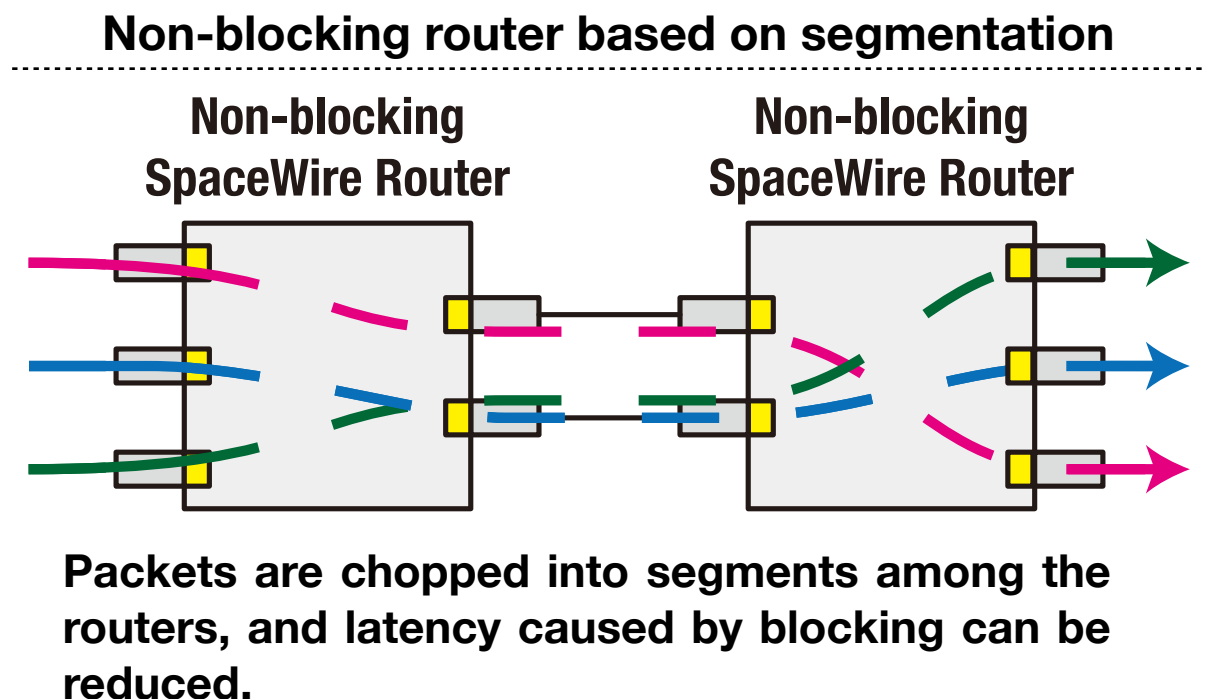
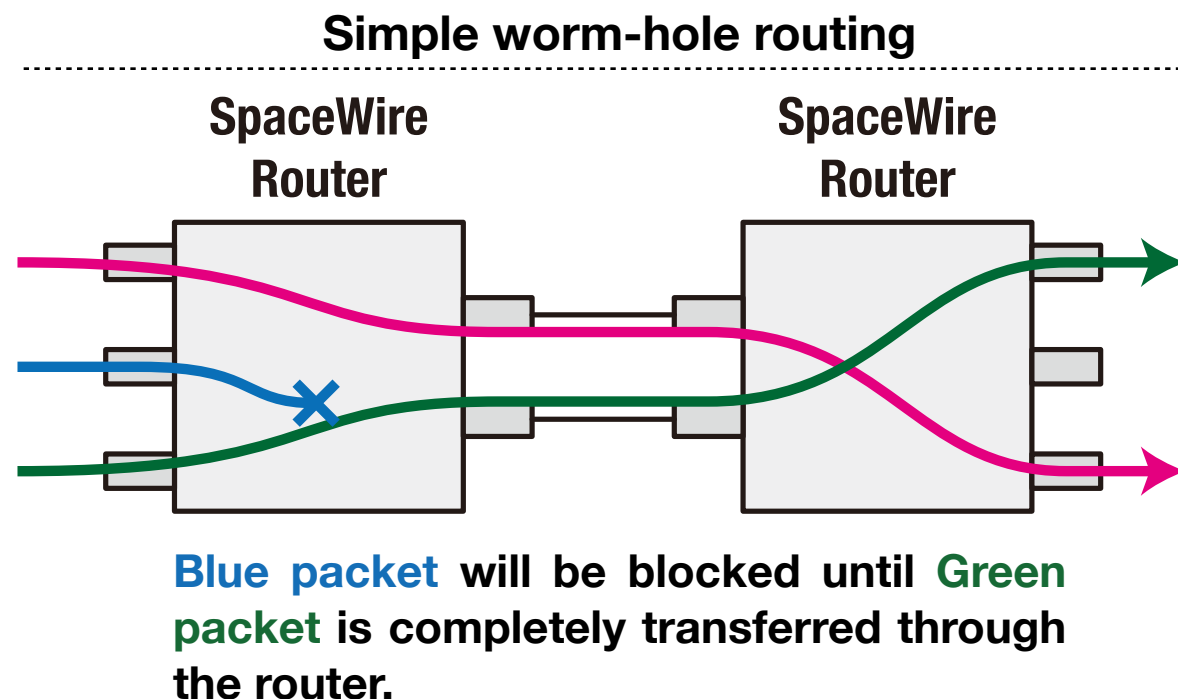
# Consideration on non-blocking SpaceWire Router

## Requirements

- When applying SpaceWire to the spacecraft bus, determinism, timeliness, reliability are strongly required (as has been discussed repeatedly).
- SpaceWire-D will be a baseline for deterministic design.
- QoS of a network should be guaranteed even when a node fails.
  - SpaceWire Router developed based on the current standard can block packets when a destination port is occupied by earlier packet (worm-hole routing).
  - Bubbling-idiot node can block important routers.
  - Links connecting two routers can be a bottle neck in terms of blocking.
- Solution for the blocking should have minimum impact on existing end nodes.

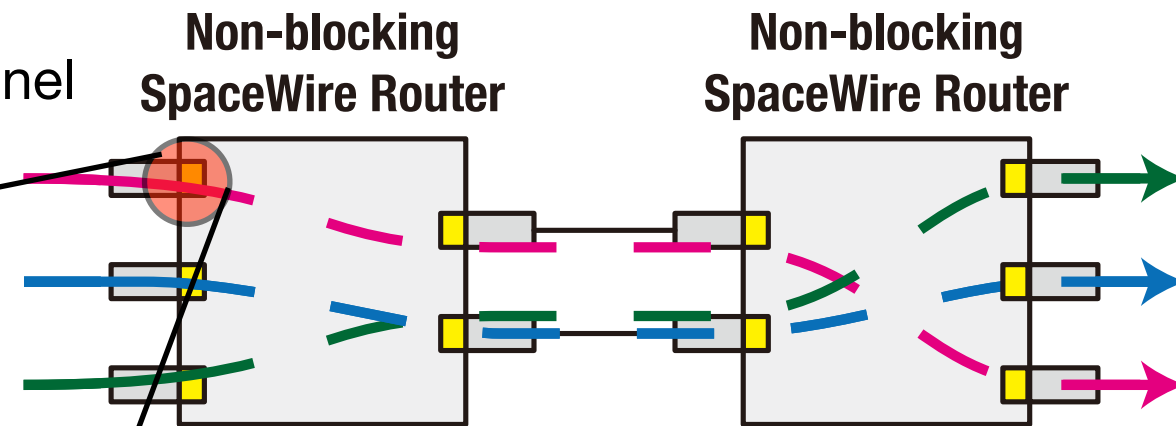
## Background

- SpaceFibre has a virtual channel capability, and this could be reimported to SpaceWire Router.



# Tentative structure of non-blocking router

- Based on Framing, Retry, and Multi-lane layers of SpaceWire. (see previous WG discussions)
- May require additional configuration to open virtual channel between router ports.
- Prototype implementation from Q2-3 2013.



## SpaceFibre layer structure

