



SpaceWire-D

Trade-Off Criteria

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1 Introduction

1.1 AIMS AND OBJECTIVES

The aim is to list the trade-off criteria to be used in evaluating different options for SpW-D.

1.2 GUIDE TO DOCUMENT

Section Error! Reference source not found. lists the trade-off criteria.

1.3 ACRONYMS AND ABBREVIATIONS

AD Applicable Document

AOCS Attitude and Orbit Control System

ECSS European Cooperation for Space Standardization

GNC Guidance and Navigation Control

QoS Quality of Service

RMAP Remote Memory Access Protocol

RMW Read/Modify/Write

SpW SpaceWire

1.4 APPLICABLE DOCUMENTS

The documents applicable to this specification are listed in Table 1-1.

	Table 1-1: Applicable Documents		
REF	Document Number	Document Title	
AD1	ECSS-E-ST-50-12C Formerly ECSS-E50-12A, January 2003	SpaceWire: Links, nodes, routers and networks	
AD2	ECSS-E-ST-50-51C	SpaceWire Protocol Identification	
AD3	ECSS-E-ST-50-52C	SpaceWire Remote Memory Access Protocol	

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2 TRADE-OFF CRITERIA

In this section the trade-off criteria (principal requirements) for SpaceWire-D are presented.

Deterministic

- Deterministic to 1 ms (at link speeds of 50 Mbits/s or higher)
- Be able to collect data from several (e.g. ten) sensors within 1 ms

Range of performances depending on application need – lower link speed implies lower performance

Efficient use of link bandwidth

- Be able to achieve link bandwidth utilisation of at least 50% when transferring large amounts of data (e.g. 100 kbytes in length). The higher the link utilisation the better.
- Be able to achieve link bandwidth utilisation of at least 20% when sending and receiving short commands (4 bytes in length). The higher the link utilisation the better.

Random node access

• Be able to decide at run time which nodes you want data from.

Support concurrent data transfers

Linear increase in overall bandwidth with additional devices initiating data transfers.

Simple

- · Easy to explain.
- Concise specification.
- · As few operating modes as possible.
- Simple specification of options and parameters to support interoperability.

Operate using existing SpaceWire devices

- As few constraints as possible on existing devices.
- Target devices no functional constraints and minimal performance constraints. Fewer or more relaxed performance constraints are better.

Be capable of detecting errors

- Transaction not completed in time.
- Failure of link to an initiating node?

Be capable of recovering from errors??

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- Maintaining determinism e.g. double transmission, possibly over different paths?
- Without maintaining determinism.