

# The SpaceWire CODEC

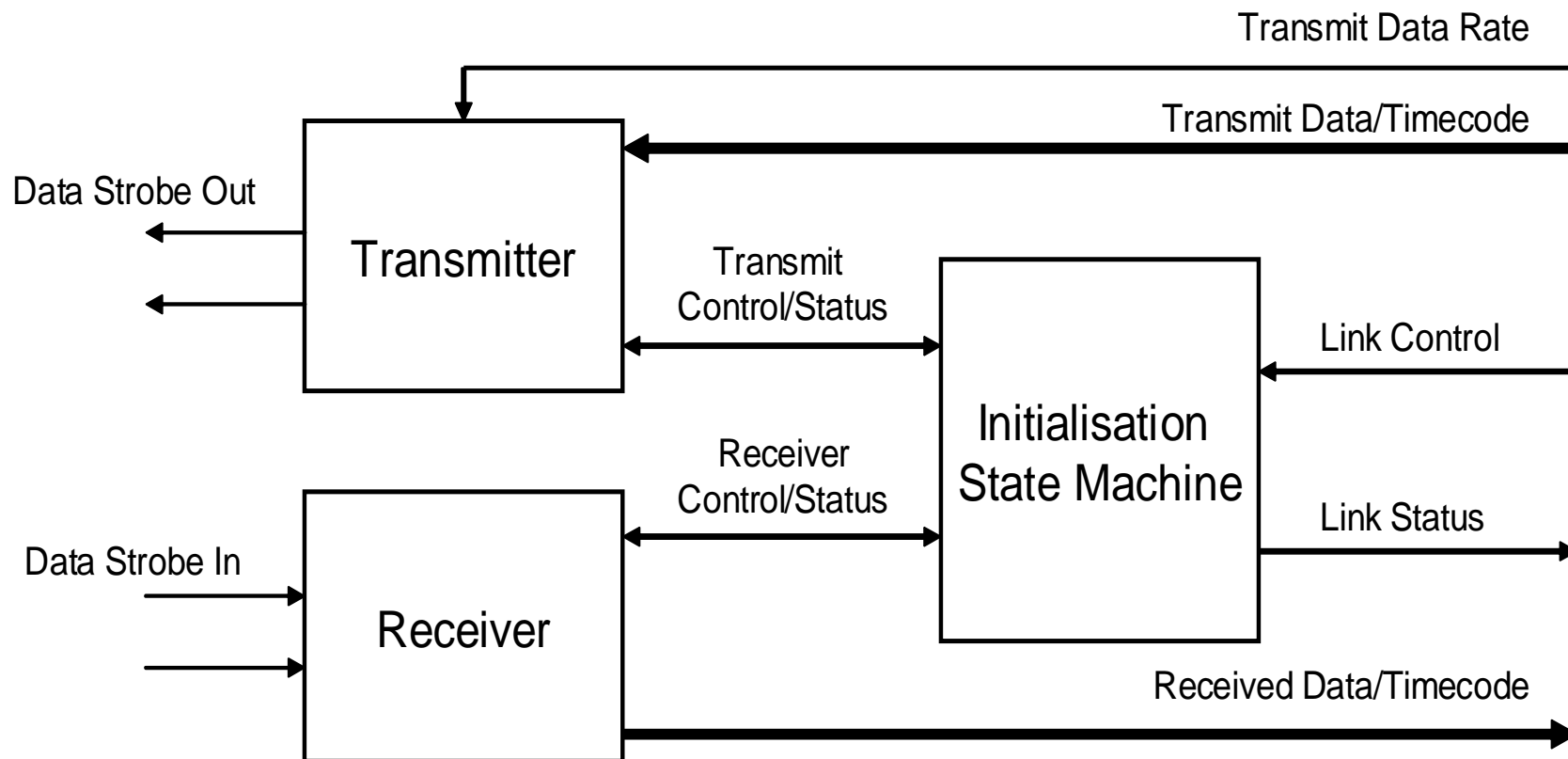
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# Introduction

- SpaceWire system
  - Nodes connected indirectly through routers or directly node to node
- SpaceWire CODEC
  - Encodes and decodes bit-stream on physical medium, SpaceWire cable.
  - Part of the data-link layer for SpaceWire systems to communicate
  - Implemented in RTL level VHDL code.
  - Compliant with ECSS-50-12A SpaceWire standard
- Goals
  - Technology independent
  - High speed operation, Low area footprint
  - Configurability to users requirements and target technology

# Architecture (1)



## Architecture (2)

- Initialisation state machine
  - Establishes a connection with other end of link
  - Enables and disables transmitter and receiver
  - Timeout counters to determine state changes
- Transmitter
  - Bit-stream serialisation using shift register
  - Variable data rate and transmit clock selection
  - Next character selection dependent on initialisation state and current requests
  - Allowed to send data characters when FCTs are received

# Architecture (3)

- Receiver
  - Performs receiver clock recovery
  - Decodes input bit-stream.
  - Controls receiver buffer credit operations.
  - Resynchronises received characters to receive buffer clock
- Internal Error Recovery
  - Error recovery is performed when a link error is detected.
  - Recovers the tx and rx data buffers due to link disconnection
    - Transmitter may be in the middle of sending a packet
      - Packet is flushed from transmitter buffer.
    - Receiver may have been receiving a data packet.
      - Received packet is truncated with an error end of packet
    - Any outstanding FCT characters are added back to space available in receiver buffer counter.

# Serial Interface

- SpaceWire uses data-strobe encoding
  - Strobe changes when data retains value for one bit-period
  - Efficient receiver clock recovery using Data xor Strobe at the expense of one extra signal wire.
- Transmitter serial interface can be configured for
  - Single data rate
    - One bit of information shifted for each transmit clock period
    - Simplest implementation
  - Double data rate
    - Two bits of information encoded for each transmit clock period
    - Extra complexity as two bits of data must be multiplexed onto the output pin for each clock period

# Configuration Interface

- Main Goal of the VHDL SpaceWire CODEC
  - Tailor the VHDL to suit the users target hardware and application.
- Target hardware comes under two main headings
  - ASIC devices
  - PLD/FPGA devices
- Main factors affecting SpaceWire CODEC design
  - Number of clock nets or clock routing resources
  - Most efficient data storage method
  - Size of receiver buffer
  - Speed requirements
  - Area requirements

# Pipelining Configuration

- Pipelining defines the insertion of flip-flops to increase performance
  - Extra logic is required for the pipeline flip-flops, greater area footprint
  - One cycle of latency is added to the transmitter when transmitting a data character and to the receiver when receiving a data character
- Increase in transmit speed compensates for extra logic and latency
- Simple data-rate comparison on a Xilinx Virtex-e device with no constraints on the logic

| Type          | Area footprint |      | Max transmit rate |             | Max input bit rate,<br>Receive clock*2 |
|---------------|----------------|------|-------------------|-------------|--|
|               | FLIP-FLOPS     | LUTS | SDR               | DDR         |  |
| Non-pipelined | 257            | 352  | 93 mbits/s        | 186 mbits/s | 285 mbits/s                            |
| Pipelined     | 267            | 354  | 141 mbits/s       | 282 mbits/s | 345 mbits/s                            |



# Transmit Clock (1)

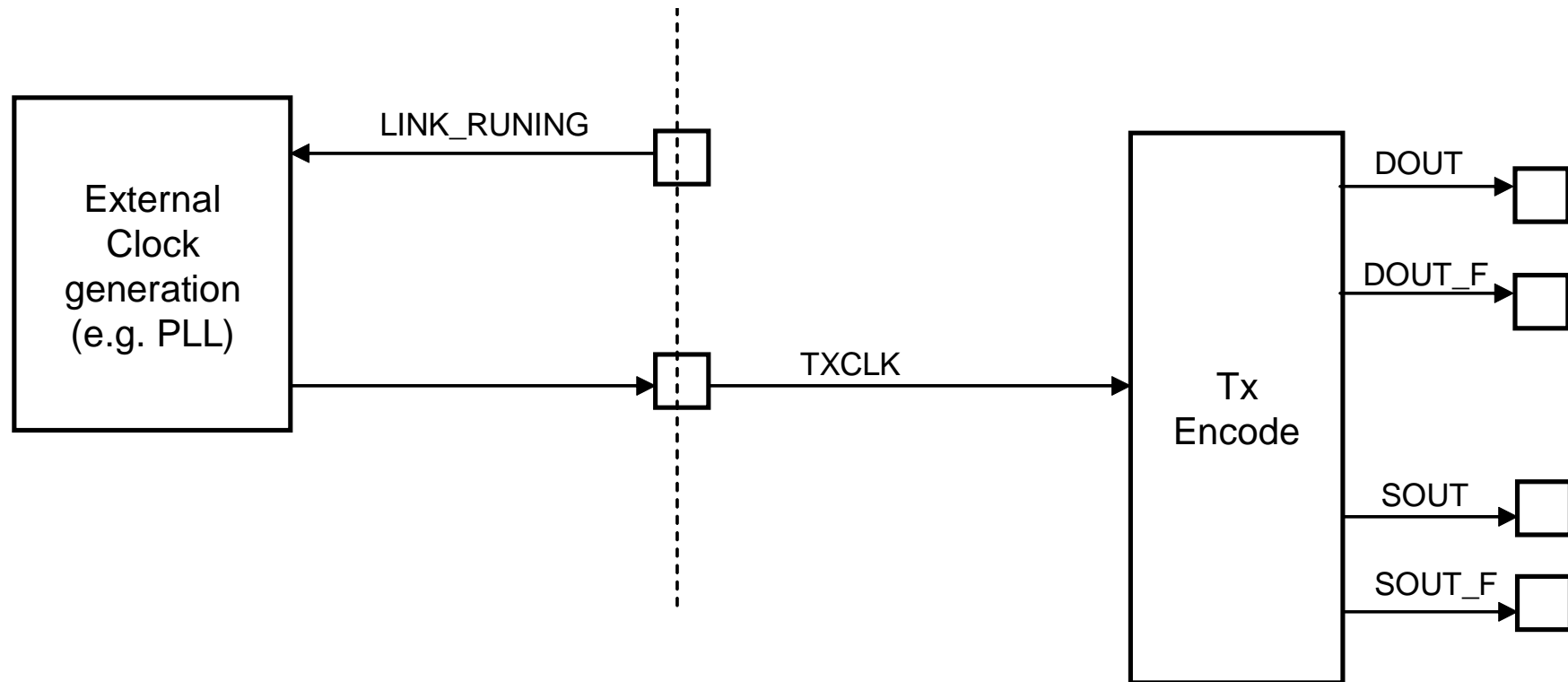
- The transmit clock frequency determines the maximum serial output bit-rate.
  - Maximise target hardware capabilities to achieve maximum data rate
- CODEC transmitter constraints:
  - Transmit clock
    - System clock or independent transmit clock
      - Set dependent on number of clock sources and nets available
  - Variable data rate
    - External, Internal clock divider or internal clock enable
      - Set dependent on the users variable data rate generation requirements
  - Default 10Mbits/s transmit rate
    - Internally generated using variable data rate generator or external crystal
      - Set dependent on the clock sources, system and transmit clock frequencies.

## Transmit Clock (2)

- All transmit Clock Configurations

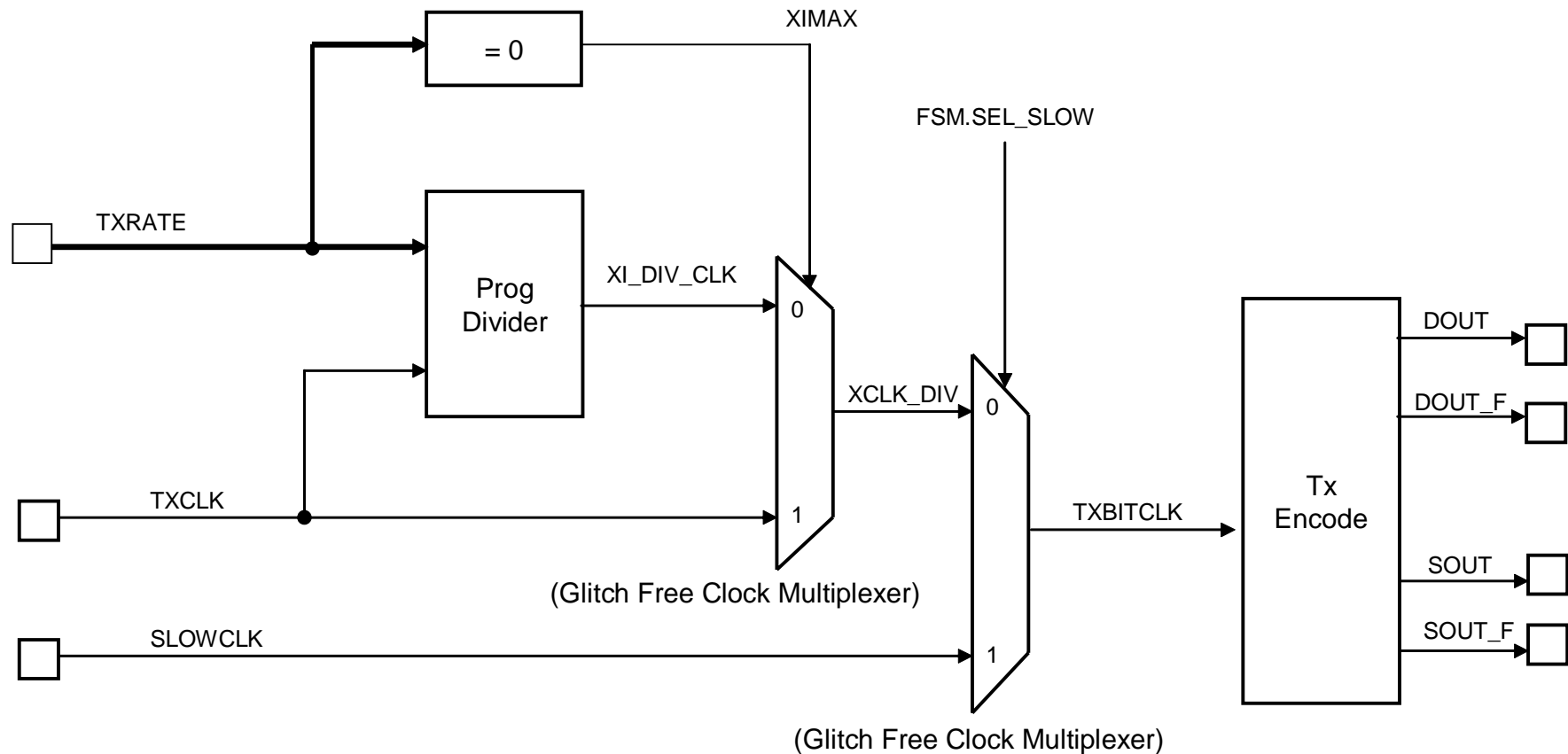
| Symbolic name     | Input clock    | Default 10/5MHz   | Variable data rate |
|-------------------|----------------|-------------------|--------------------|
| SYS_DEFAULT       | System Clock   | System Clock      | System Clock       |
| SYS_SLOWCLK       | System Clock   | External 10/5 MHz | System Clock       |
| SYS_SLOWCLK_DIV   | System Clock   | External 10/5 MHz | Clock divider      |
| SYS_DIV           | System Clock   | Clock divider     | Clock divider      |
| SYS_EN            | System Clock   | Clock enable      | Clock enable       |
| TXCLK_DEFAULT     | Transmit Clock | Transmit Clock    | Transmit Clock     |
| TXCLK_SLOWCLK     | Transmit Clock | External 10/5 MHz | Transmit Clock     |
| TXCLK_SLOWCLK_DIV | Transmit Clock | External 10/5 MHz | Clock divider      |
| TXCLK_DIV         | Transmit Clock | Clock divider     | Clock divider      |
| TXCLK_EN          | Transmit Clock | Clock enable      | Clock enable       |

# Transmit default configuration



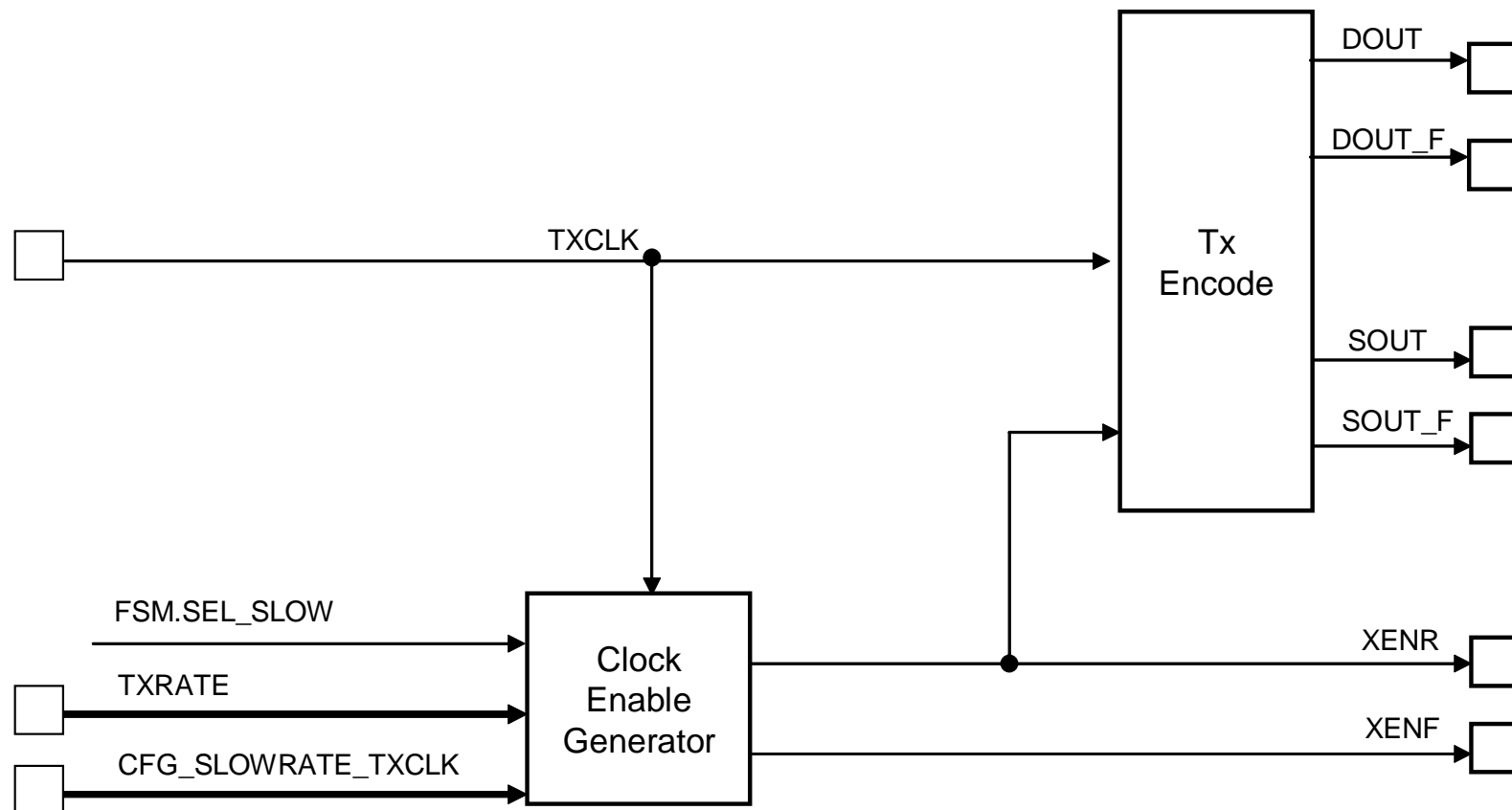
- Transmit clock is input from external clock generator

# Internal Divider With External 10Mbits/s



- Internally generated variable transmit clock

# Internal Clock Enable



- D input of transmitter flip-flops is gated by clock enable signals

# Variable Data Rate

- Default bit rate for all configurations
  - (No external 10Mbits/s clock)

$$10Mbits = \frac{TxMaxBitRate}{(CFG\_SLOWRATE\_TXCLK + 1)}$$

- Variable bit rate for all configurations

$$TxNormalBitRate = \frac{TxMaxBitRate}{(TXRATE + 1)}$$

# Receive Buffer Configuration

- Receiver buffer stores received data characters
  - User sets size of receive buffer  $2^n$ 
    - 8 bytes to maximum user buffer size (e.g. 32 bytes, 1Kbytes, 1Mbytes, etc.)
  - User sets maximum outstanding data characters,  $\geq 8$  and  $\leq 56$
- Receiver credit count operations performed internally by CODEC:
  - Uses an internal FCT pointer which moves ahead of read and write pointers for outstanding data characters and reserved buffer space
  - Request transmitter to send one FCT when:
    - unreserved space in buffer, up to maximum buffer size, and
    - not currently requesting maximum outstanding data characters
- Credit error is detected when a data character is received when not requested.
  - FCT pointer is moved back to write pointer position (No outstanding data characters)

# Receive buffer data re-synchronisation

- Received data characters resynchronised to receive buffer clock domain
  - Double flip-flop resynchronisation control signals used
  - At maximum bit rates the time taken to resynchronise data characters is greater than the time taken to receive
  - Internal 4 byte buffer used to store received data characters until the data is written to the receive buffer
- Design aims/goals
  - No internal data storage!
- Use most common storage methods
  - Latches for ASIC cell based devices
  - Flip-flops/RAM inference for FPGA based devices



# Latch Implementation

- Three stage latch cell write is performed
  - Receiver clock cycle 1 : Setup data, address
  - Receiver clock cycle 2 : Perform write strobe
  - Receiver clock cycle 3 : Hold data, address
- Reception of empty packet (double EOP/EEP) violates three clock cycle write rule.
  - CODEC can be configured to ignore empty packets
- Reception of <data><eop><data> violates three clock cycle write rule (<eop> = 2 receive clock cycles)
  - CODEC receiver delays EOP/EEP by one clock cycle

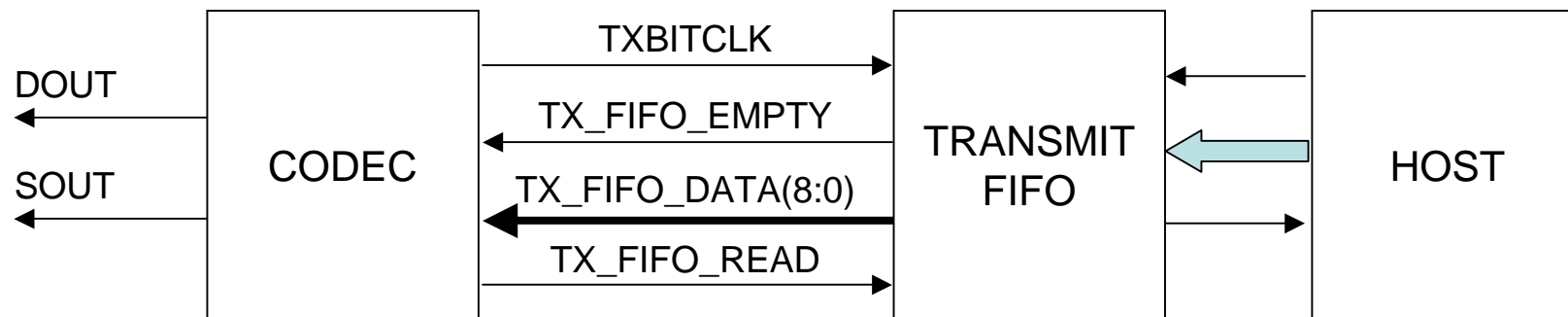
# Host Interface

- Link control functions implemented as in SpaceWire standard
  - Auto-start link
    - Wait for other end of link to make connection
  - Start link
    - Attempt to make a connection with the other end of the link
  - Disable link and force disconnection
- Status outputs
  - Status outputs synchronous with system clock
  - Provide a snapshot of the CODEC

# Status Outputs

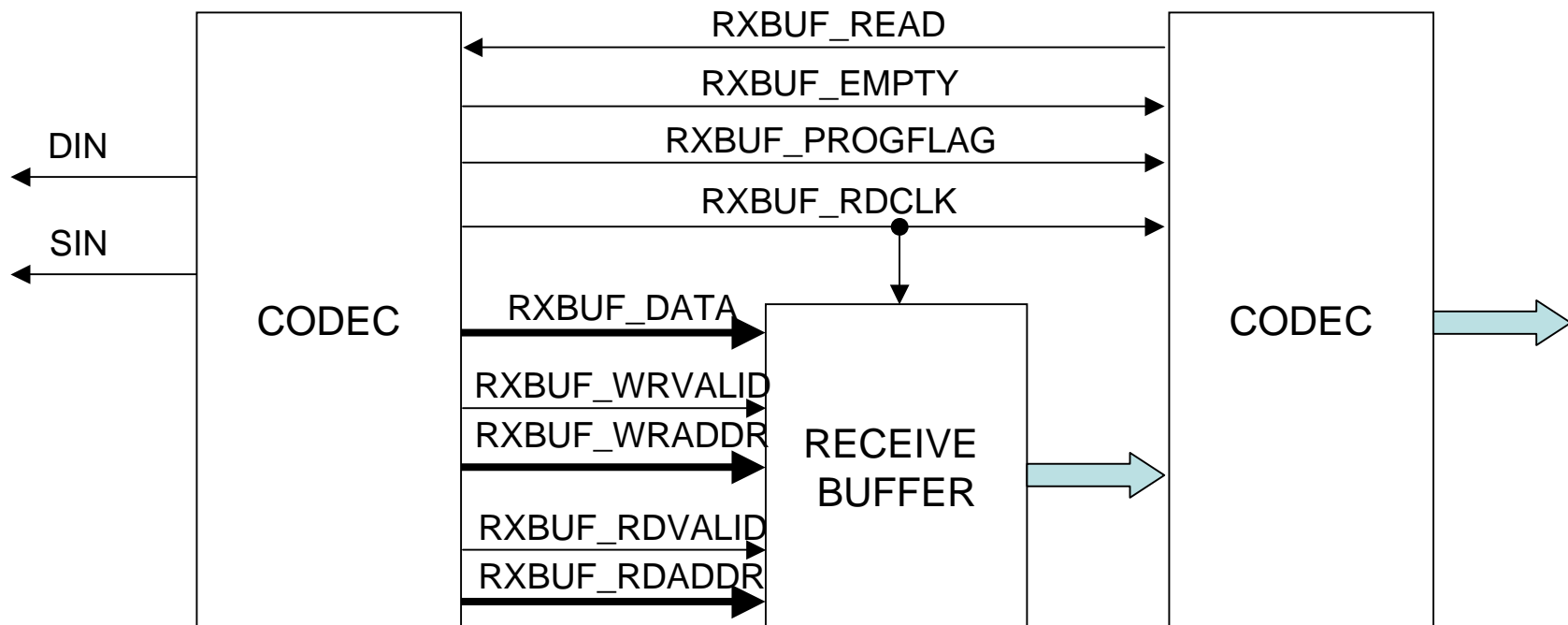
| Signal      | Description  |
|-------------|--|
| STATUS(0)   | Disconnect error.  |
| STATUS(1)   | Parity error.  |
| STATUS(2)   | Escape error.  |
| STATUS(3)   | Receiver credit error.   |
| STATUS(4)   | Transmitter credit error.  |
| STATUS(7:5) | Interface state encoded into three bits (6 states)                   |
| STATUS(8)   | Interface state machine is in the <i>Run</i> state.                  |
| STATUS(9)   | Receiver got NULL. Remains asserted after first NULL.                |
| STATUS(10)  | Receiver got FCT. Remains asserted after first FCT                   |
| STATUS(11)  | Receiver got N-chars. Remains asserted after first N-Char            |
| STATUS(12)  | Receiver got Timecodes. Remains asserted after first Timecode        |
| STATUS(13)  | Transmitter has credit to send one more data character               |
| STATUS(14)  | N-char sequence error (N-char received before link state is Run)     |
| STATUS(15)  | Timecode sequence error (Timecode received before link state is Run) |

- FIFO interface to host system
  - Transmit FIFO is implemented externally using technology specific data storage



- Synchronous empty and read signals
  - Synchronous to TXBITCLK which may be asynchronous to host clock
- Good implementation uses FIFO with independent read and write clocks

- FIFO interface to host system
  - Data buffer is implemented externally using users technology specific storage method
  - CODEC implements synchronous FIFO interface



# Receive buffer clock frequency (1)

- Parallel data output from the CODEC written to the receive buffer using:
  - system clock or independent read buffer clock
- Receive buffer clock can be slower to save power, for example.
  - 200Mbits/s input bit-rate
  - Stream of one byte packets causes, on average, one data character available every 35ns
    - Resynchronisation buffer smoothes data flow
  - Minimum receive buffer clock frequency to support data rate in this case is  $1/35\text{ns} = \sim 28.571\text{ MHz}$
- For the same setup
  - Stream of four byte packets causes, on average, one data character available to receive buffer every 44 ns.
  - Minimum receive buffer clock frequency to support input data rate in this case is  $1/44\text{ns} = \sim 22.727\text{ns}$

# Receive buffer clock frequency (2)

- From previous slide it can be seen that the minimum size of packets and the input bit-rate determine the minimum receive buffer clock
- Minimum read clock =

$$\frac{1}{\left( \frac{(MinNumData \times Tdata) + Teop}{MinNumData + 1} \right)}$$

- In terms of maximum input bit rate =

$$\frac{1}{\left( \frac{Trxbuf\_clk \times NumPktNchars}{NumPktBits} \right)}$$

# Performance and latency

- Expected performance
  - 200Mbits/s Router ASIC device
  - 200Mbits/s University of Dundee components
  - Placed and routed at 400Mbits/s in a Virtex 2 -6 speed grade device
- Latency
  - Minimum transmit latency is 2 transmit clock cycles
  - Minimum receive latency is
    - 2 receive clock cycles +
    - 2 receive buffer clock cycles



# Conclusions

- SpaceWire standard ECSS-50-12A compliant SpaceWire CODEC
- Features
  - High speed operation
  - Configurable to meet users requirements
  - Ease host integration
  - Technology independent