



Architecture for using SpaceWire links in a bus configuration

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Guiding Concept

Integrate fault-tolerant concepts in
SpaceWire networks

Overview

- Fault-Tolerant Network Concepts
- SpaceWire & Fault-Tolerant Networking
- SpaceWire Multiple Access Schemes
- SpaceWire Internetworking
- Demonstration Application

Fault Tolerance

- Graceful accommodation of faults
- Fault detection, isolation, resolution
- Layered system required

Network Advantages

- Networking helps provide layering
- Permits distribution of computing elements (functional redundancy)
- Dramatically reduces wiring harness mass
- Rapid functional prototyping (standards based)

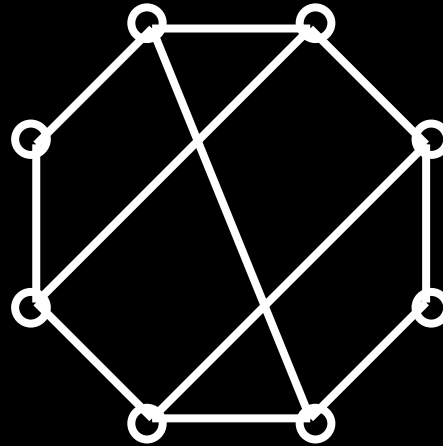
Fault-Tolerant Network

- Architecture required that allows:
 - Broadcast ability
 - Protection against failed nodes
 - Protection against failed connections

Fault-Tolerant Network

- Bus network:
 - Provides broadcast ability
 - Cannot remotely isolate nodes
 - No protection against failed connections

Fault-Tolerant Network



➤ Mesh Network

- Allows isolation of nodes
- Complex routing algorithms presently used
- Broadcast data is not typical mode of operation

Broadcast Mesh

- Combines the functionality of both.
- Relies on byte (symbol/subpacket)-forwarding.
- Simple rules allow dynamic route around failed links and nodes. No routing tables.
- Requires certain services from point-to-point link system.
- Each node has at least two endpoints for point-to-point links.
- Each node acts as a router.

Link Layer Requirements

- Point-to-point
- Detection of errors
 - Carrier loss
 - Bit-errors on octets
- Packet framing
- Error reporting
- SpaceWire offers all of these features up to the exchange level

Byte Forwarding

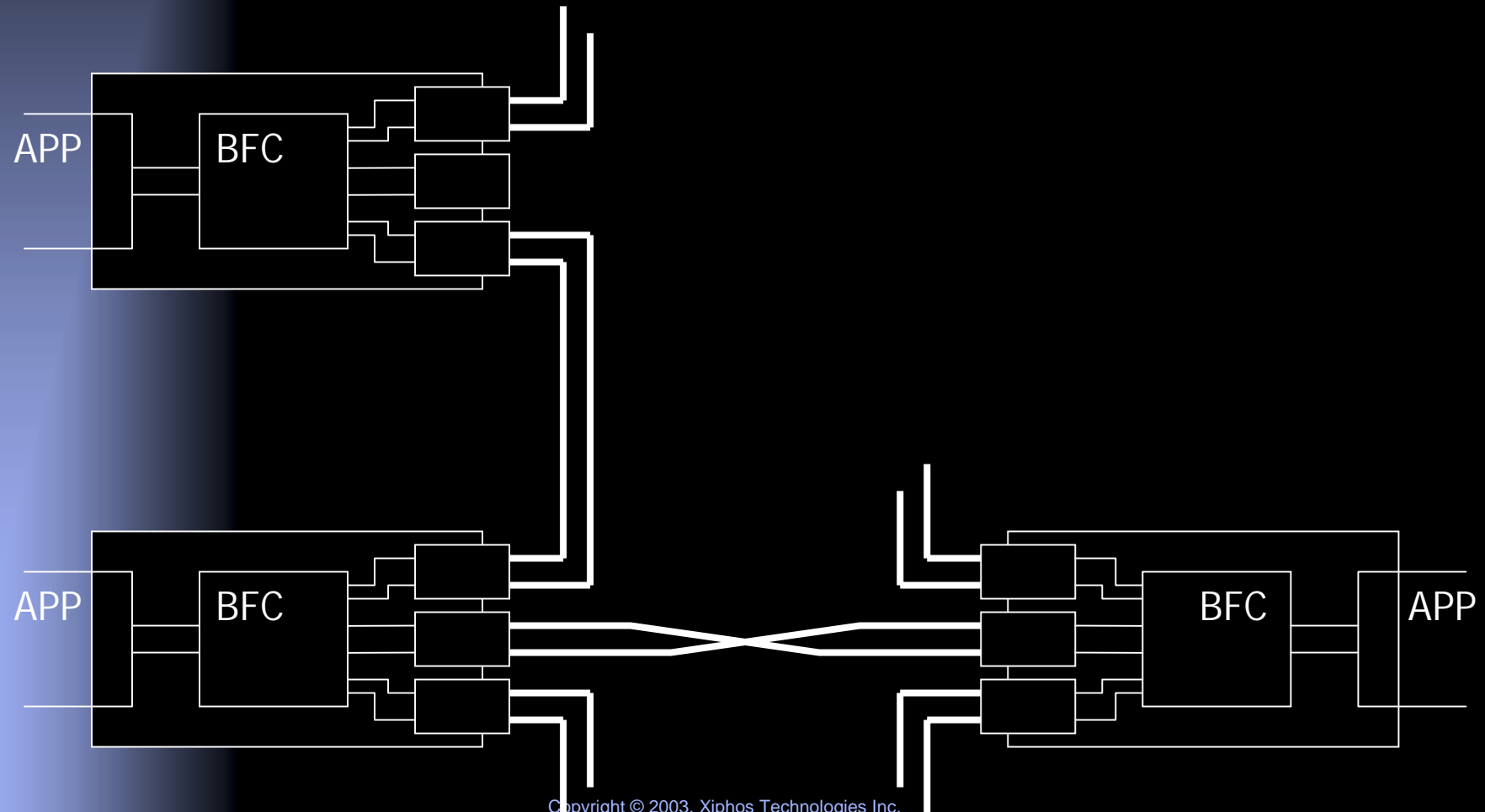
- Underlying principle is 'byte-forwarding'
- **Sending:** When a node determines that it is permitted to send a packet on the network, it starts sending on all links

Byte Forwarding

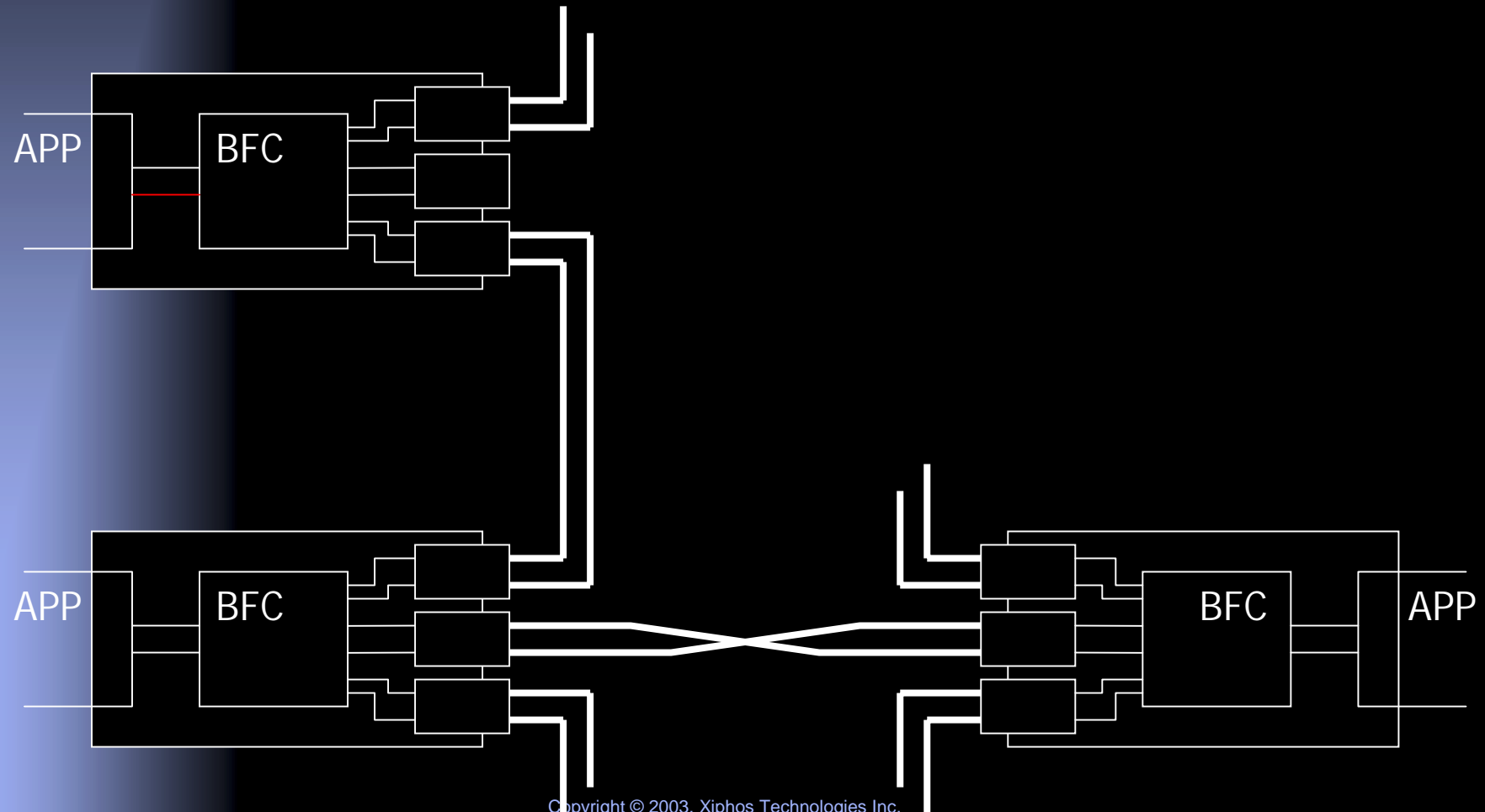
➤ Forwarding

- Every node listens on all ports and once a packet starts to arrive, designates the initial receive port as the 'source' port.
 - Once a byte is correctly received from the source port, it is transmitted simultaneously on all ports, including the source port.
- A node does not forward a packet until the entire previous packet has been forwarded/received
- All nodes reflect what they receive, receipt of an EOP (framing) signal is required on every port

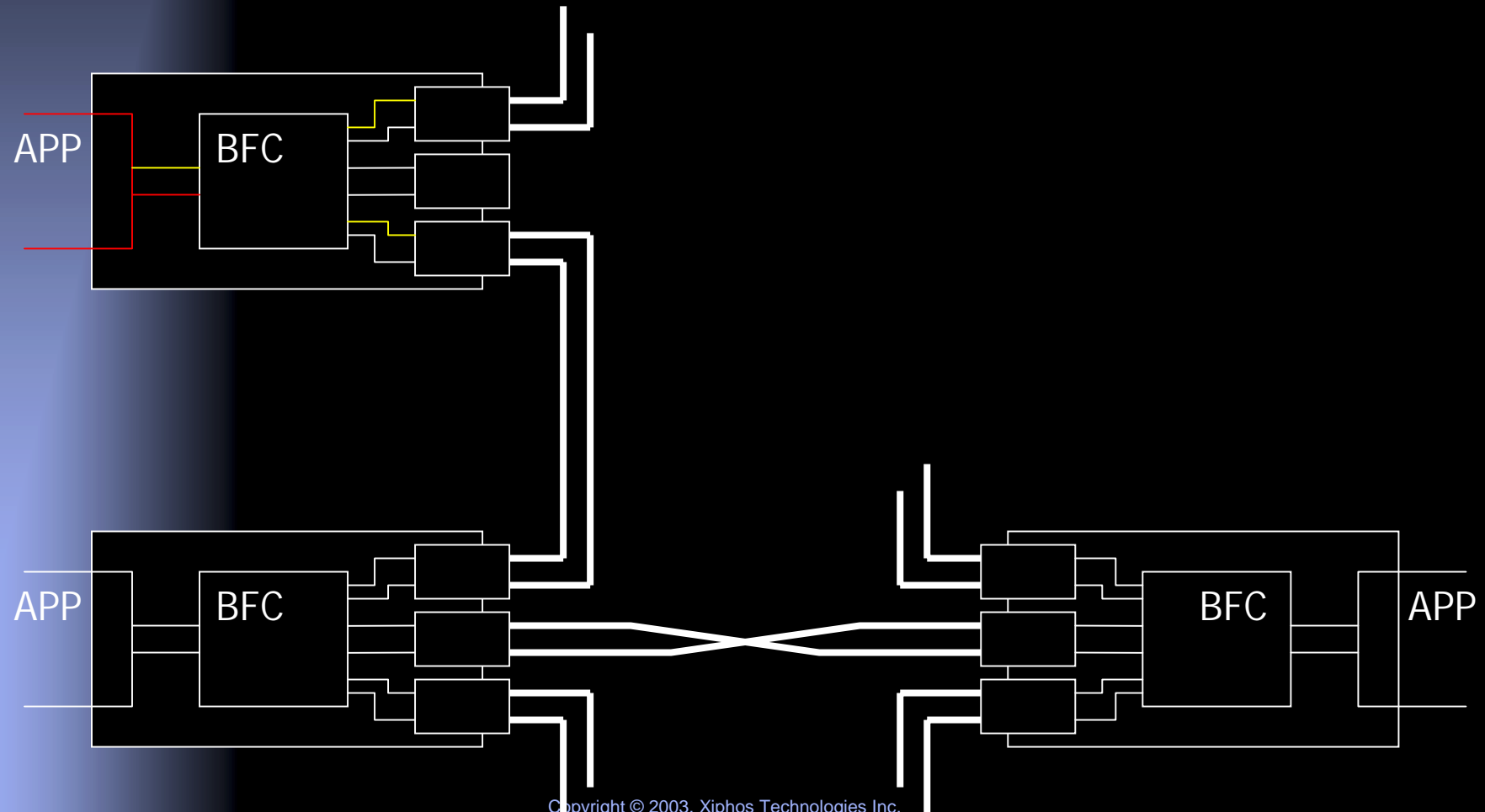
Closer View



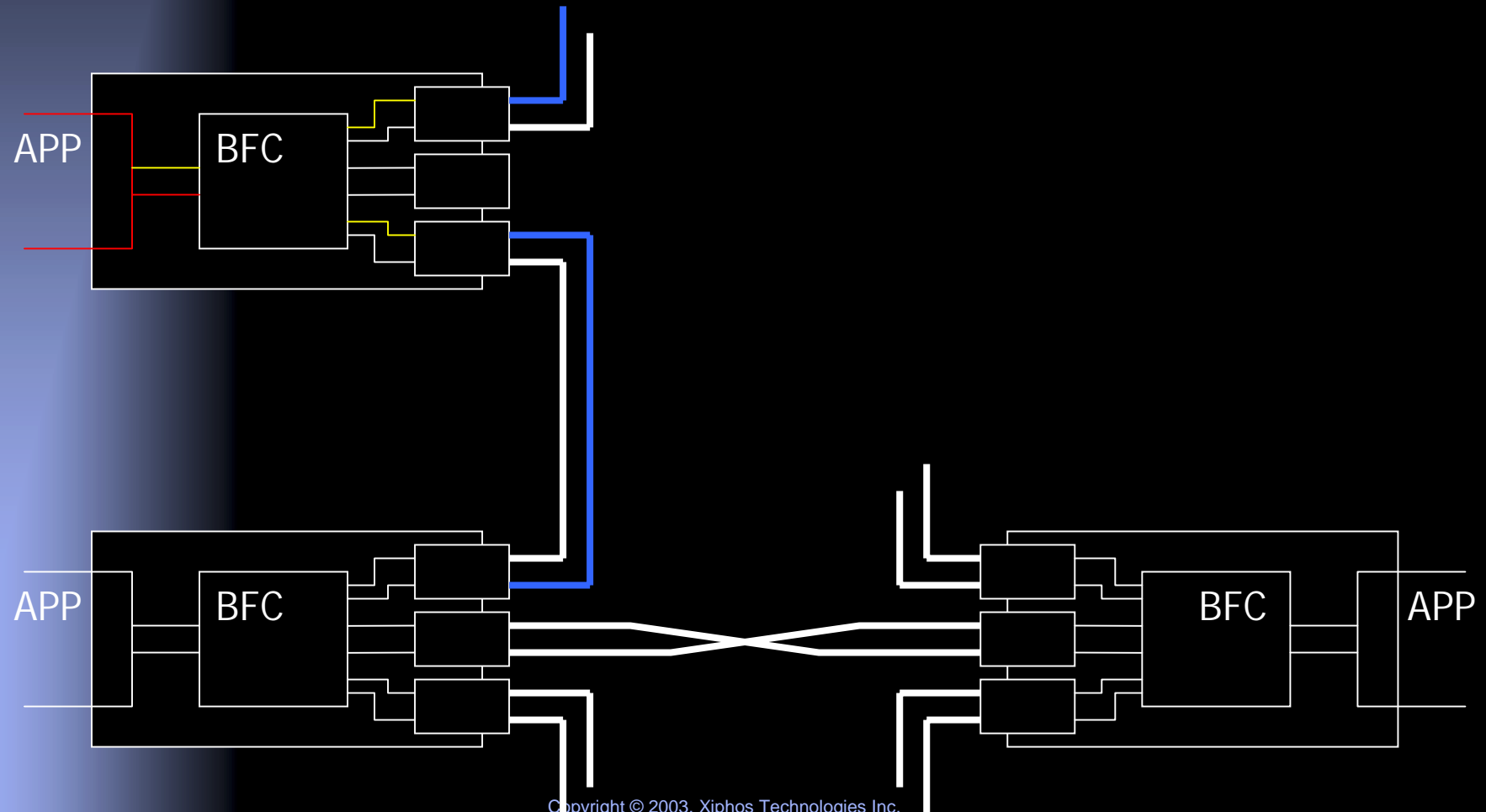
Application Sends



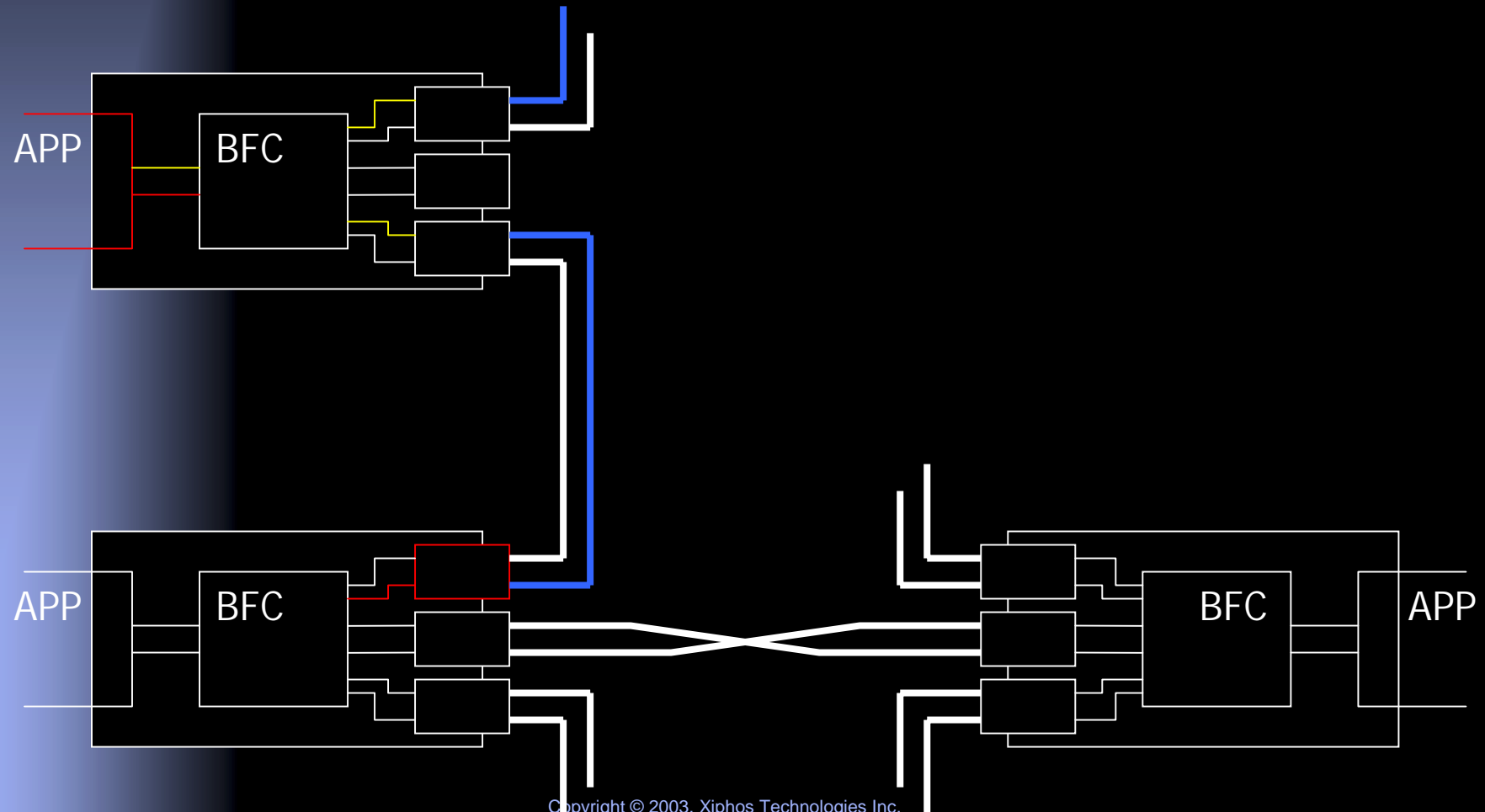
BFC Forwards



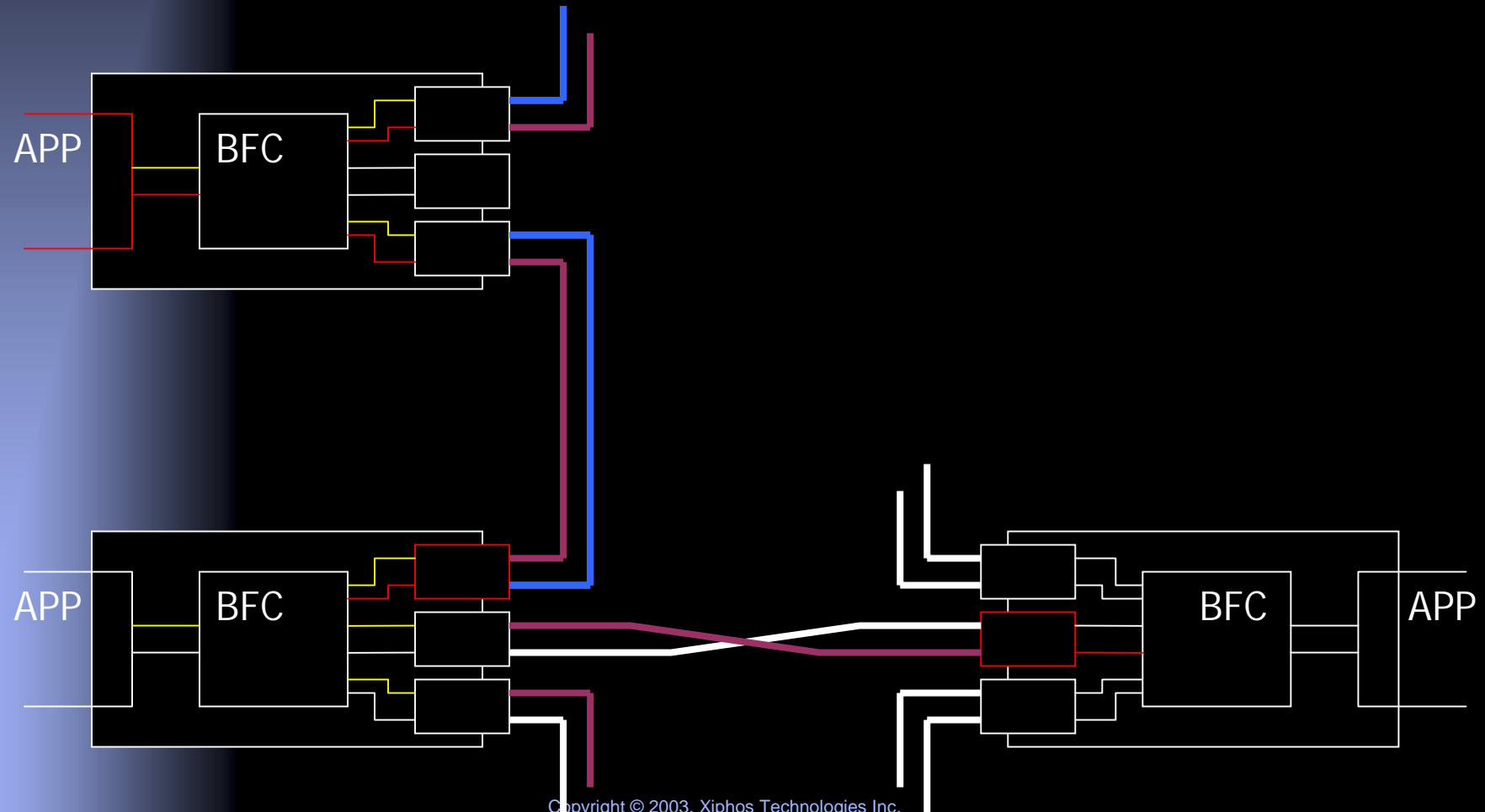
Links Send



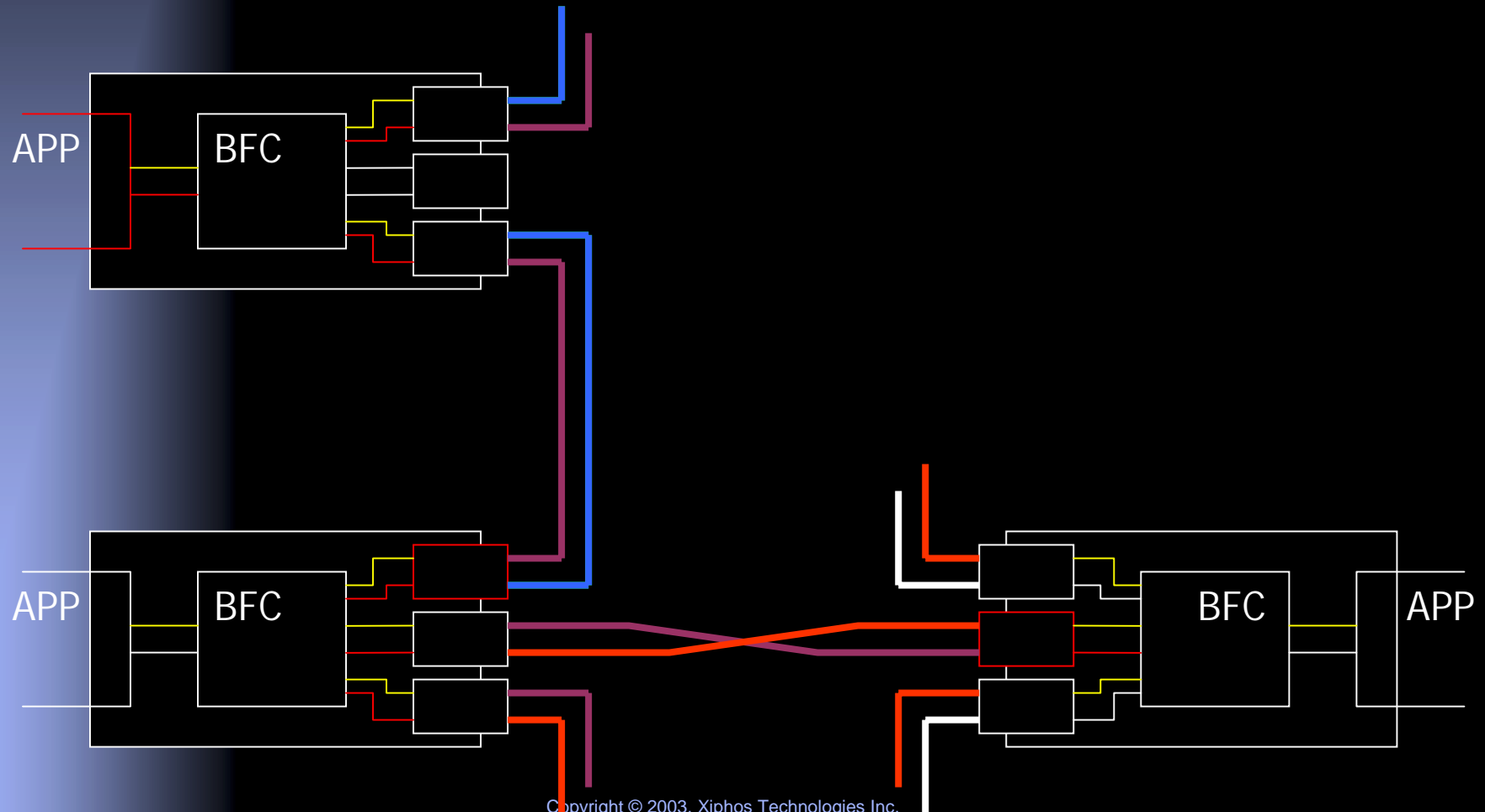
Source Link Established



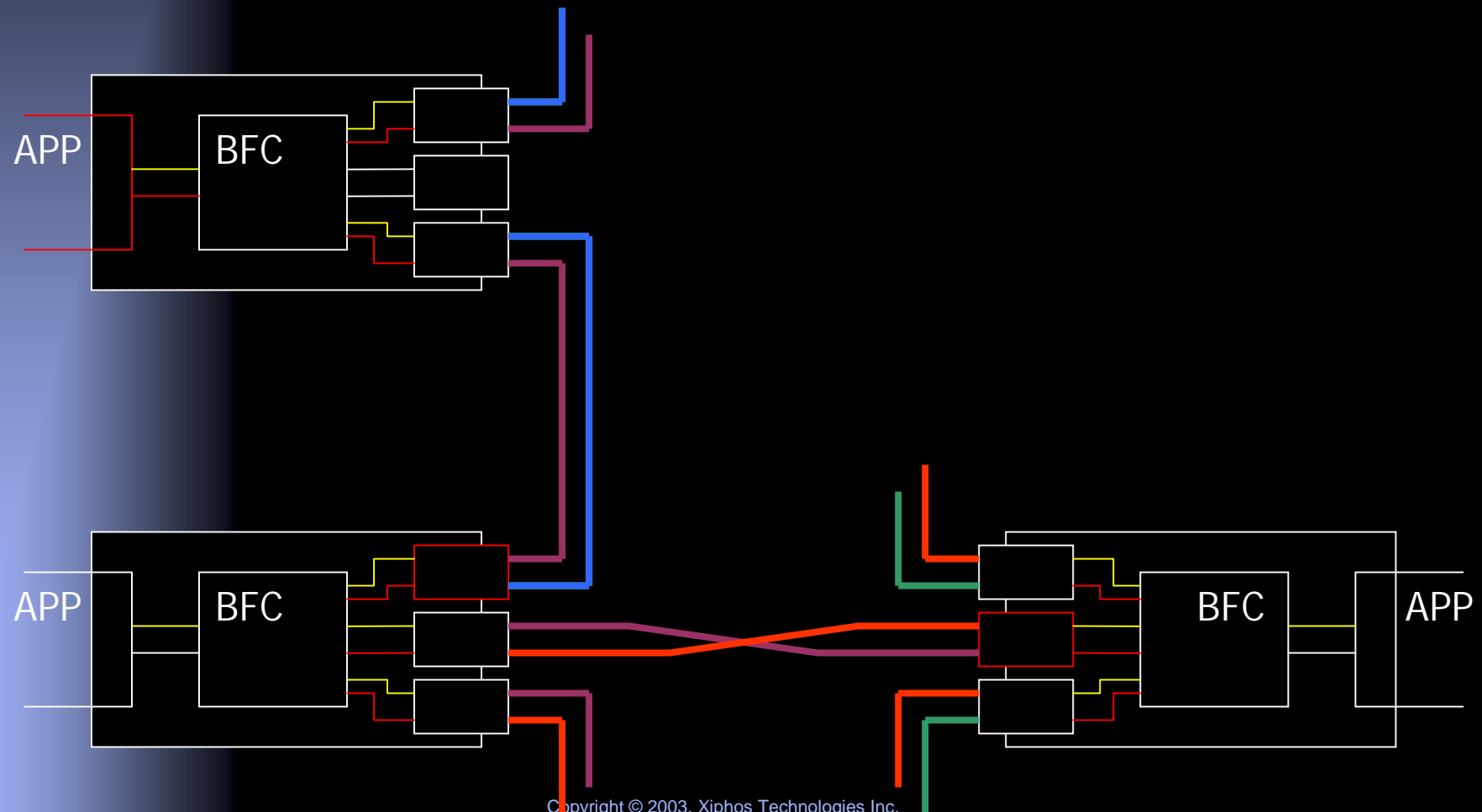
2nd BFC Forwards



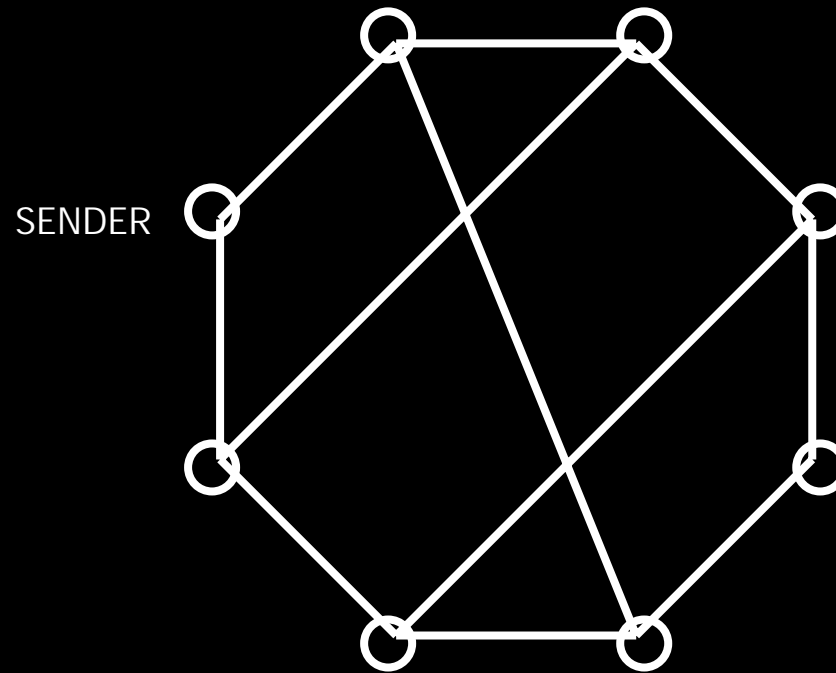
3rd BFC Forwards



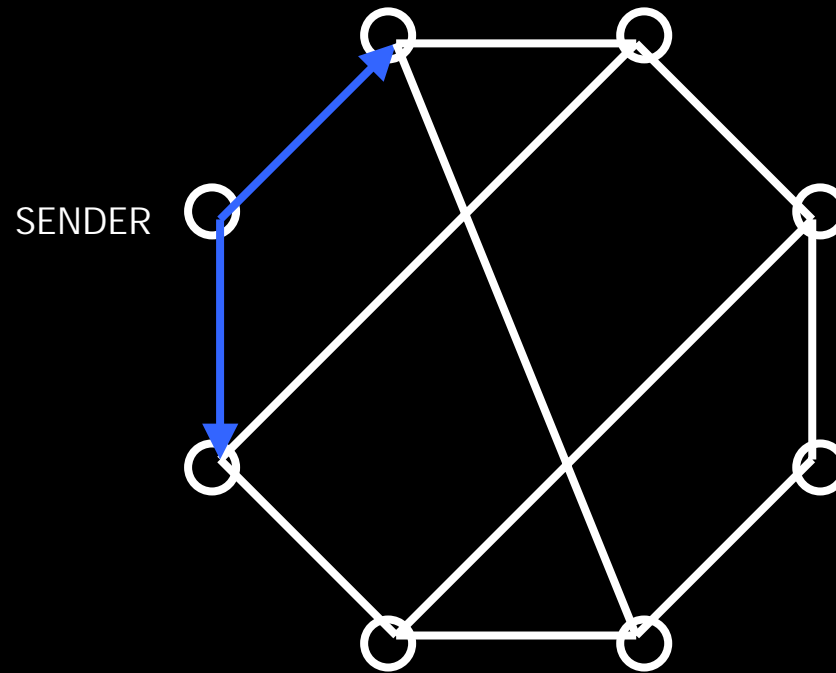
4th BFC Forwards



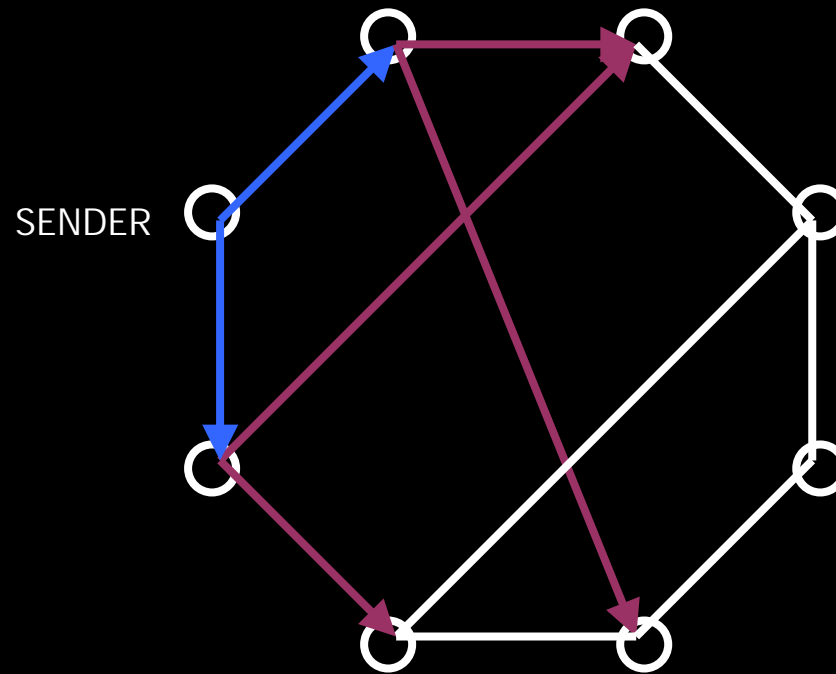
Chordal Ring Example



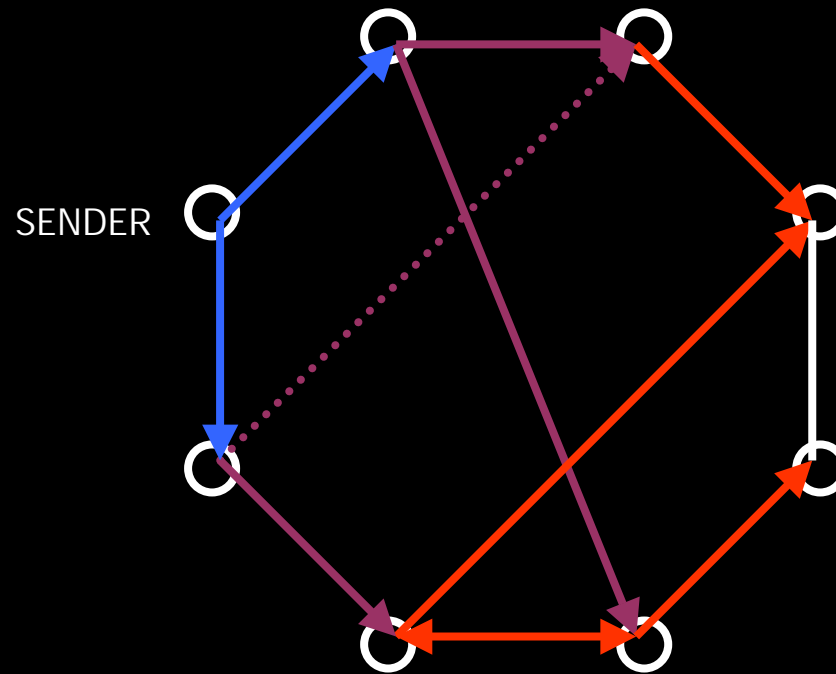
Chordal Ring Example



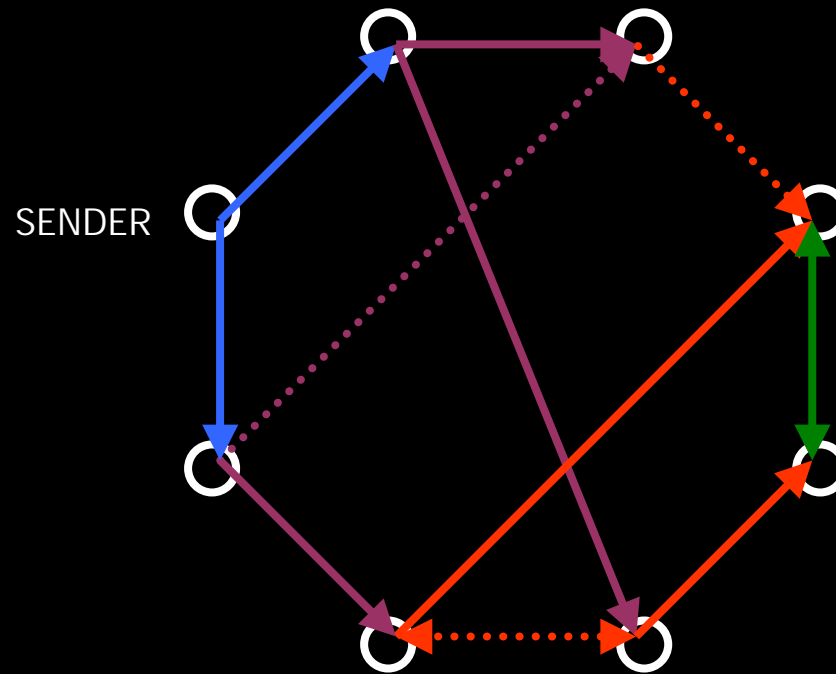
Chordal Ring Example



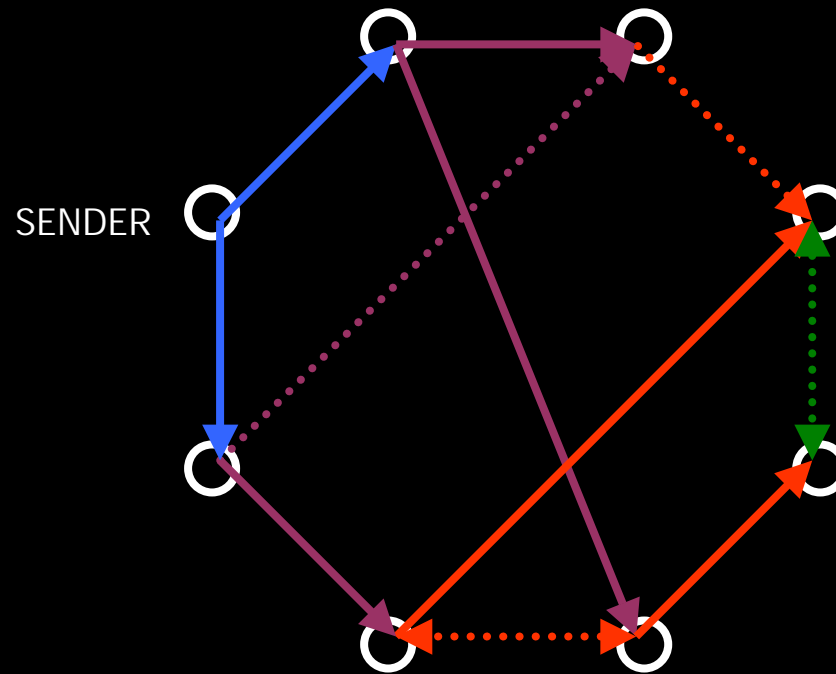
Chordal Ring Example



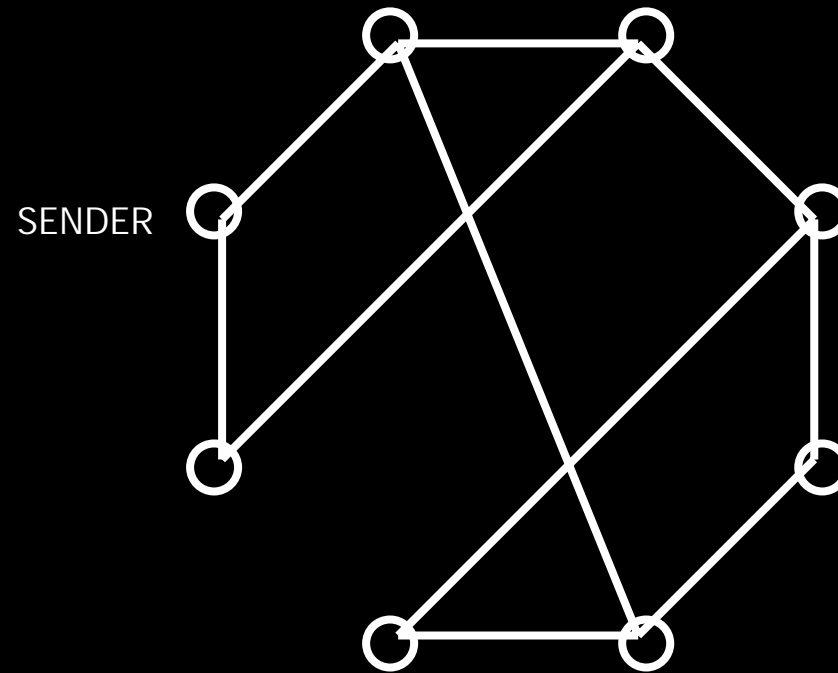
Chordal Ring Example



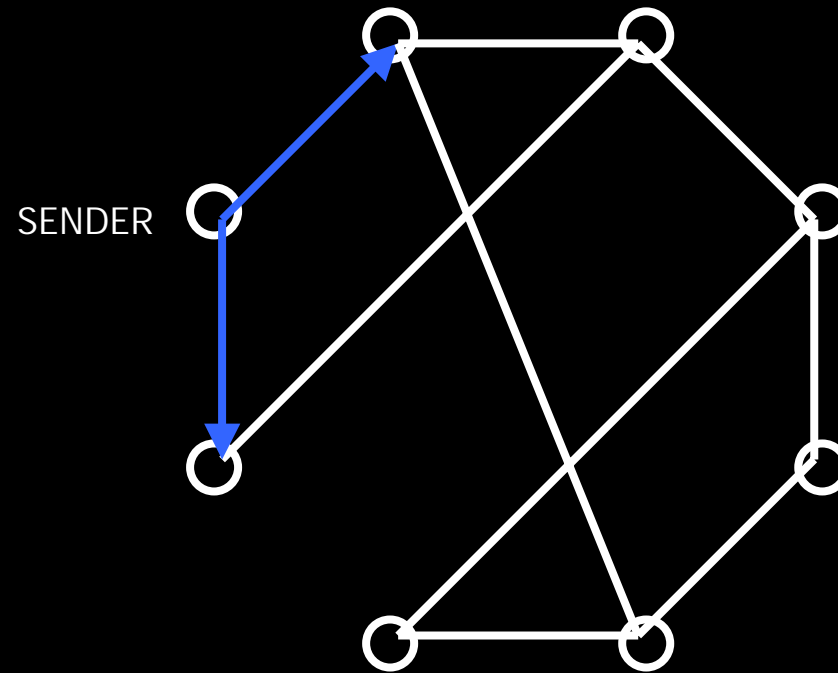
Chordal Ring Example



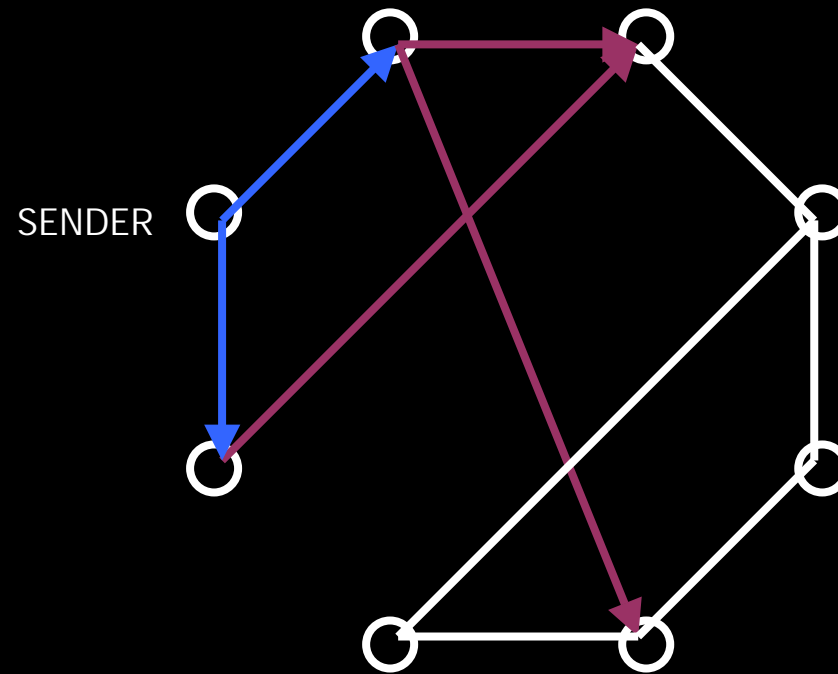
Failed Link



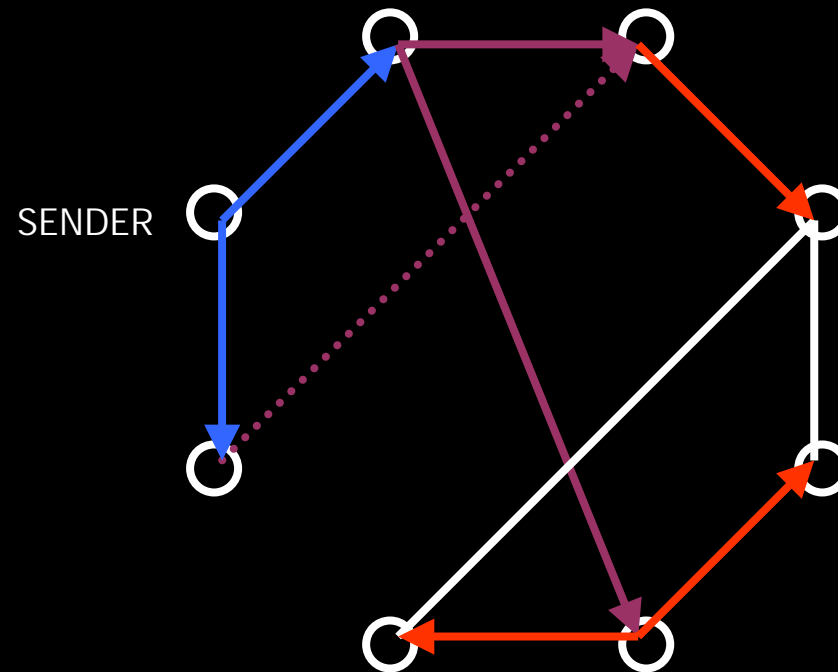
Failed Link



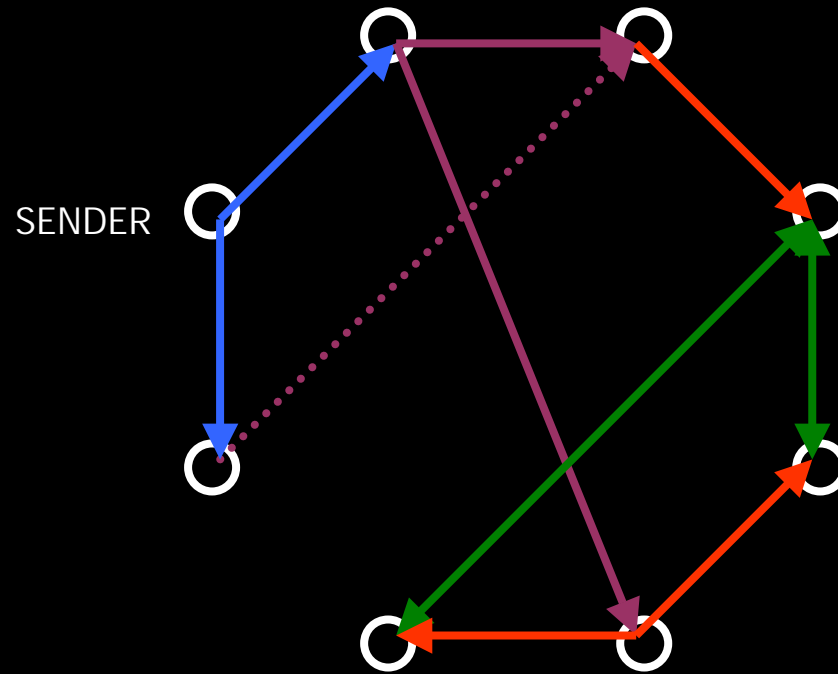
Failed Link



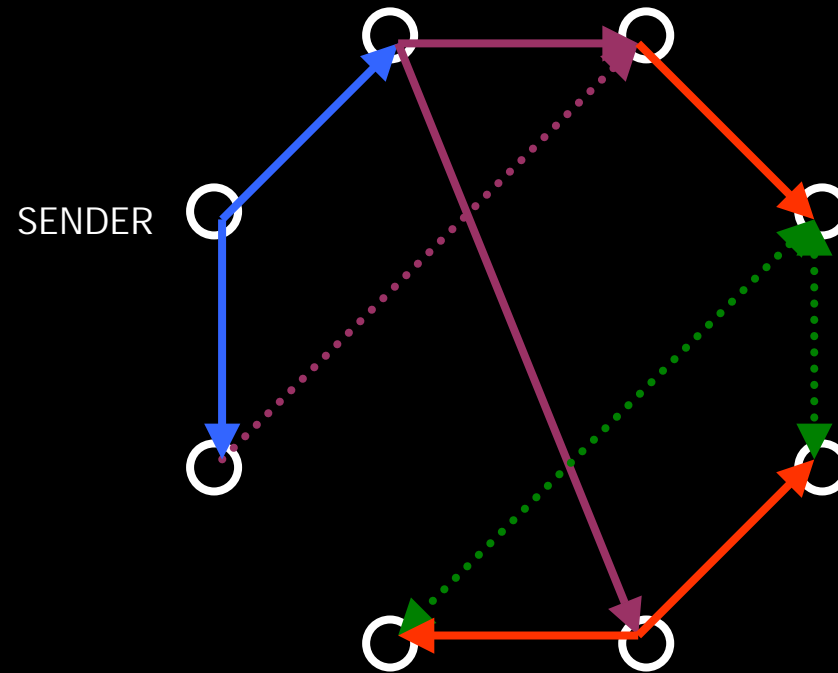
Failed Link



Failed Link



Failed Link



MAC Schemes

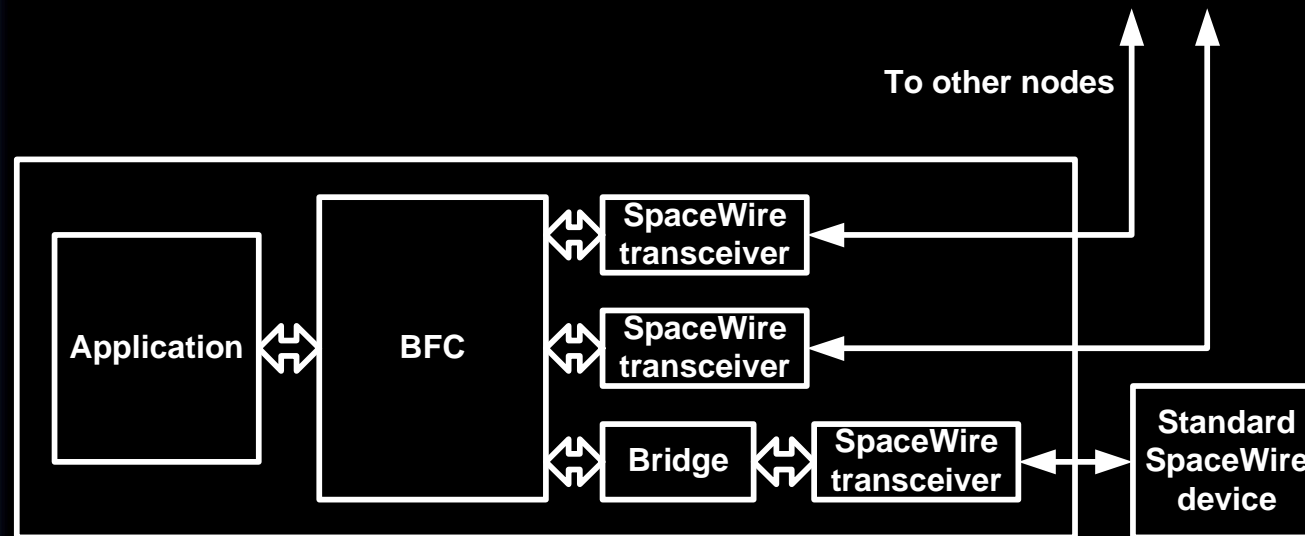
- Non-contention based MACs
 - Master-slave
 - Token ring
- Contention based MACs
 - Ethernet style
 - Packet collision detection

Internetworking

- Standard SpaceWire devices are not SpaceWire bus compatible
 - They do not forward incoming packets
 - They only expect to receive packets that are directed to them

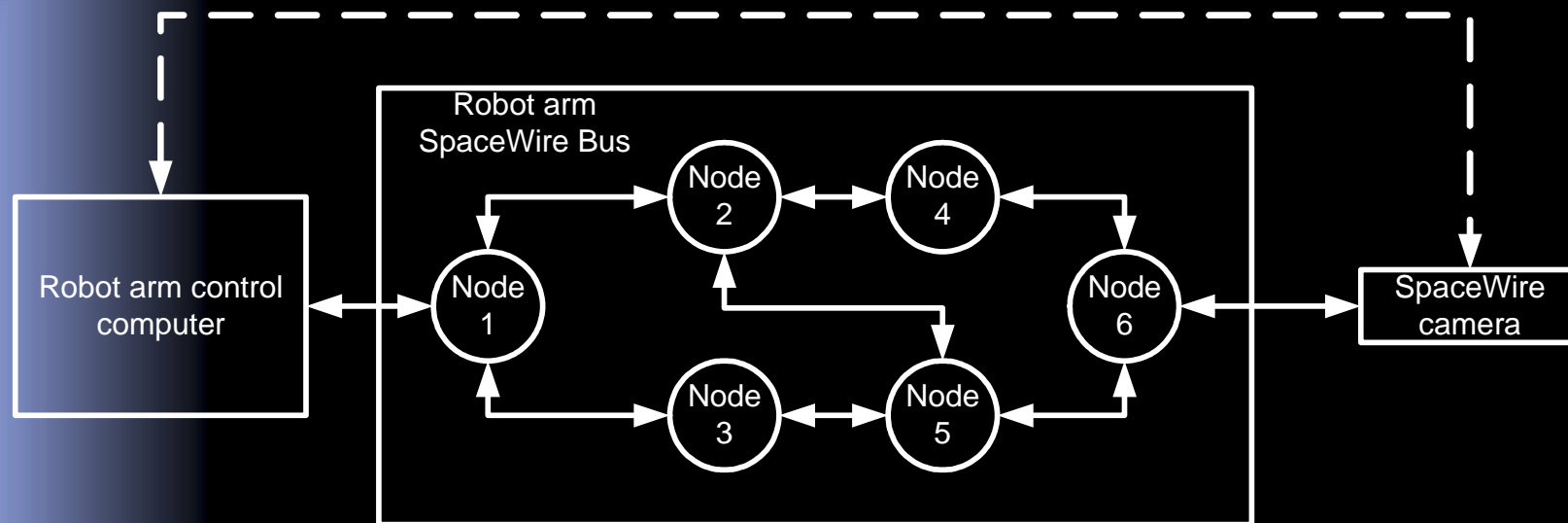
Internetworking

- Solution : design a bridge with two functions:
 - Forward all incoming packets
 - Send to the standard device connected only packets that are directed to it



Internetworking

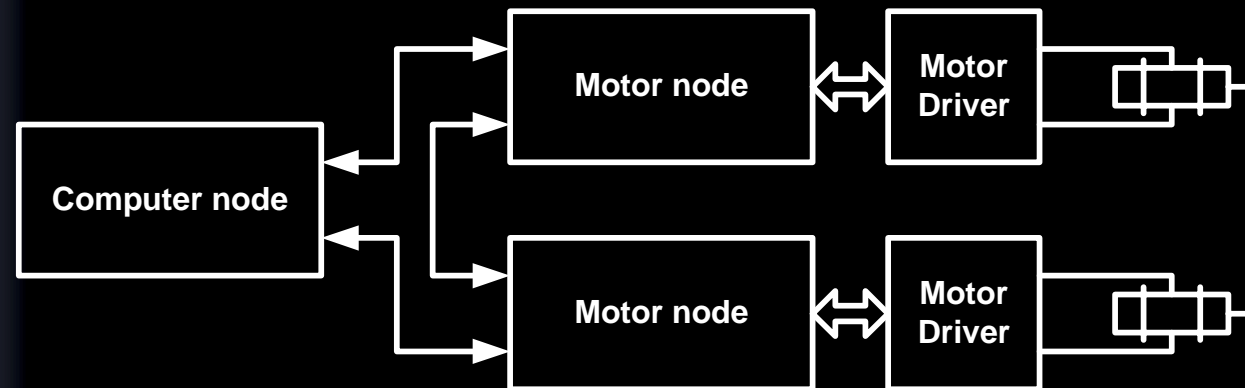
- Advantages of internetworking
 - May use less cabling resources
 - Provide SpaceWire bus advantages to standard devices



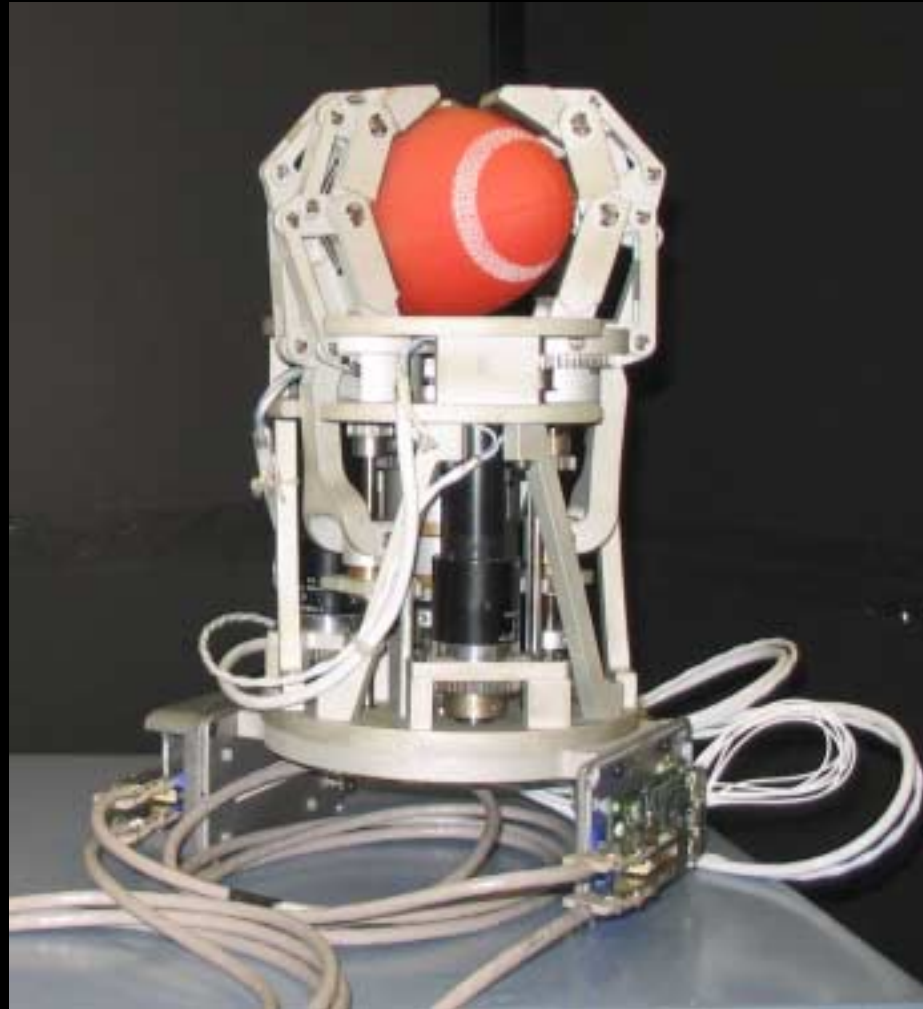
Demonstration Application

➤ SARA H

- Three-digit robotic hand using two drive motors
- Uses one Q5 as a computer node and two Q5s for motor control
- A SpaceWire bus connects all Q5s together



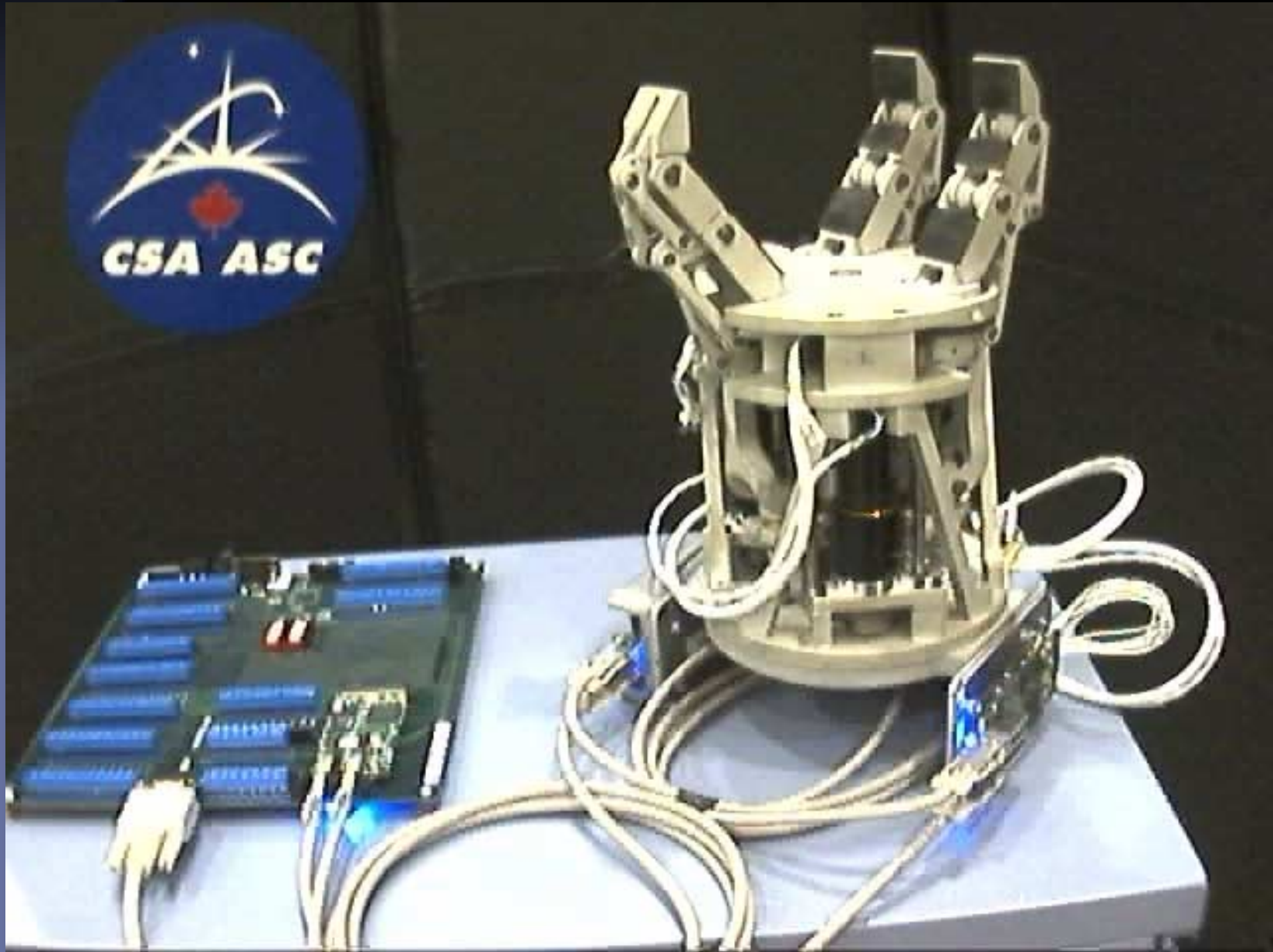
Demonstration Application



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Demonstration Application

- Node fault tolerance
 - Failed nodes are detected and replaced transparently by the backup node
 - Motor nodes exchange internal data (PID integrator value) to smooth transition to/from backup nodes
- Network fault tolerance
 - One cable can be disconnected without affecting the system behavior





Demonstration Application

- Each SARA node contains a SpaceWire bridge to connect standard SpaceWire devices



Questions?

Reach out and
control something.

